

Lecture 2: Universality Classes of Nonlinear Networks

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Let's use the same strategy as last time to compute moments for a nonlinear network. New things:

- allow for Gaussian biases, $E[b_i] = 0$, $E[b_i b_j] = C_b \delta_{ij}$
- two common examples for $\sigma(z)$ are
 - ReLU ("rectified linear unit") $\sigma(z) = \max(0, z)$
 - $\sigma(z) = \tanh(z)$

Will see that these belong to different universality classes of network behavior

Recall the NN forward equations:

$$z_i^{(l)} = b_i^{(l)} + W_{ij}^{(l)} x_j, \quad z_i^{(l+1)} = b_i^{(l+1)} + W_{ij}^{(l+1)} \sigma(z_j^{(l)})$$

We start by computing the 2-point function:

$$E[z_{i_1, \alpha_1}^{(l)} z_{i_2, \alpha_2}^{(l)}] = E[(b_{i_1}^{(l)} + W_{i_1 j_1}^{(l)} x_{j_1, \alpha_1})(b_{i_2}^{(l)} + W_{i_2 j_2}^{(l)} x_{j_2, \alpha_2})]$$

[cross-terms vanish since W and b are independent]

$$= (C_b + \frac{C_w}{n} \vec{x}_{\alpha_1} \cdot \vec{x}_{\alpha_2}) \delta_{i_1 i_2}$$

$G_{\alpha_1, \alpha_2}^{(l)}$: call this the first-layer metric

A similar calculation yields $E[z z z z]_{\text{conn.}} = 0$: first-layer distribution $p(z^{(l)} | \theta)$ is Gaussian to $\mathcal{O}(\frac{1}{n})$. If we wanted, we could write this distribution as an action,

$$p(z^{(l)} | \theta) = \frac{1}{[\det(2\pi G^{(l)})]^{n/2}} \exp\left(-\frac{1}{2} G_{\alpha_1, \alpha_2}^{(l)} \vec{z}_{\alpha_1}^{(l)} \cdot \vec{z}_{\alpha_2}^{(l)}\right)$$

which is correct to $\mathcal{O}(\frac{1}{n})$.

inverse metric

An identical computation gives the layer-to-layer marginal distribution with which we build the recursion,

$$p(z^{(l+1)} | z^{(l)}) = \frac{1}{\sqrt{\det(2\pi \hat{G}^{(l+1)})}} \exp\left(-\frac{1}{2} \hat{G}_{\alpha_1, \alpha_2}^{(l+1)} \vec{z}_{\alpha_1}^{(l+1)} \cdot \vec{z}_{\alpha_2}^{(l+1)}\right)$$

where $\hat{G}_{\alpha_1, \alpha_2}^{(l+1)} = C_0 + \frac{C_w}{\lambda} \underbrace{\sigma_{\alpha_1}^{(l)} \cdot \sigma_{\alpha_2}^{(l)}}_{\sigma(\vec{z}_{\alpha_1})}$ is a stochastic variable

since it depends on the random variables $z^{(l)}, z^{(l-1)}, \dots, z^{(1)}$

In other words, marginal distributions are Gaussian with a stochastic covariance matrix, which results in accumulated non-Gaussianities in $p(z^{(l+1)} | \mathcal{D})$

To determine the recursion, we integrate out the l^{th} layer preactivations; this is analogous to one step of RG flow.

$$p(z^{(l+1)} | \mathcal{D}) = \int \prod_i dz_i^{(l)} p(z^{(l+1)} | z^{(l)}) p(z^{(l)} | \mathcal{D})$$

We can now feel free to build up $p(z^{(l+1)})$ from its moments.

Starting with $l=2$: $\mathbb{E}[z_{i_1, \alpha_1}^{(2)} z_{i_2, \alpha_2}^{(2)}] = \delta_{i_1 i_2} \mathbb{E}[\hat{G}_{\alpha_1, \alpha_2}^{(2)}] = \delta_{i_1 i_2} (C_0 + C_w \mathbb{E}[\sigma_{\alpha_1}^{(1)} \sigma_{\alpha_2}^{(1)}])$

\uparrow expectation taken over $z^{(1)}$ and $z^{(2)}$ \uparrow only over $z^{(1)}$ \uparrow λ copies of same single-neuron expectation

$$= \delta_{i_1 i_2} (C_0 + C_w \langle \sigma_{\alpha_1}^{(1)} \sigma_{\alpha_2}^{(1)} \rangle_{G^{(1)}})$$

\uparrow Gaussian expectation w.r.t. covariance $G^{(1)}$

If we let $G_{\alpha_1, \alpha_2}^{(l)} \equiv \mathbb{E}[\hat{G}_{\alpha_1, \alpha_2}^{(l)}]$ and take the

ansatz $\mathbb{E}[z_{i_1, \alpha_1}^{(l)} z_{i_2, \alpha_2}^{(l)}] = \delta_{i_1 i_2} G_{\alpha_1, \alpha_2}^{(l)}$, we have the recursion

$$G_{\alpha_1, \alpha_2}^{(l+1)} = C_0 + C_w \langle \sigma_{\alpha_1}^{(l)} \sigma_{\alpha_2}^{(l)} \rangle_{G^{(l)}} + \mathcal{O}\left(\frac{1}{\lambda}\right)$$

\leftarrow for $l \geq 2$, $\mathbb{E}[\sigma^{(l)} \sigma^{(l)}]$ is Gaussian to $\mathcal{O}(1/\lambda)$

We can derive criticality conditions in the $n \rightarrow \infty$ limit.

Let $\lim_{n \rightarrow \infty} G = K$, so our recursion is $K_{\alpha\beta}^{(l+1)} = C_b + C_w \langle \sigma_\alpha \sigma_\beta \rangle_{K^{(l)}}$

If σ is nonlinear, e.g. $\sigma(z) = z^2$, we have

$$K_{\alpha\beta}^{(l+1)} = C_b + C_w \langle z_\alpha^2 z_\beta^2 \rangle_{K^{(l)}} = C_b + C_w (K_{\alpha\alpha}^{(l)} K_{\beta\beta}^{(l)} + 2(K_{\alpha\beta}^{(l)})^2)$$

Operator mixing
under RG!

So unlike in linear networks, we have to consider the whole 2×2 K matrix, rather than just a single input.

The diagonal component is easy because it decouples:

$$K_{00}^{(l+1)} = C_b + C_w \langle \sigma^2 \rangle_{K^{(l)}} = C_b + C_w \left[\frac{1}{\sqrt{2\pi K^{(l)}}} \int_{-\infty}^{\infty} dz e^{-\frac{z^2}{2K^{(l)}}} \sigma(z)^2 \right]$$

$g(K)$: single-variable Gaussian expectation

Find a fixed point K_{00}^* by linearizing: $K_{00}^{(l+1)} = K_{00}^* + \Delta K_{00}^{(l)}$

To first order in Δ : $\Delta K_{00}^{(l+1)} = \chi_{11}(K_{00}^*) \times \Delta K_{00}^{(l)}$

$$\chi_{11}(K) = \frac{C_w}{2K^2} \langle \sigma(z) \sigma(z) (z^2 - K) \rangle_K$$

To ensure we don't move away from the fixed point, our first

criticality condition is $\boxed{\chi_{11}(K_{00}^*) = 1}$

Note: when $\sigma(z) = z$, $g'(K) = 1$, so we recover $C_w = 1$ from last time.

If $C_b \neq 0$, we have $K_{00}^{(l+1)} = C_b + K_{00}^{(l)} \Rightarrow K_{00}$ grows linearly

\hookrightarrow semi-critical: fixed point at infinity, so should rather choose $C_b = 0$.

The constancy of K_{00} ($\Leftrightarrow \chi_{11} = 1$) ensures that norms of preactivations don't change exponentially. The off-diagonal components of K measure changes to neighb inputs. Requiring that these also not change exponentially gives a second criticality condition.

Derivation is long but straightforward: find a decomposition of $K_{\alpha\beta}$ that diagonalizes the RG evolution, and linearize about a fixed point.

$$\Rightarrow \text{require } \chi_{\perp}(K^*) = 1, \text{ where } \chi_{\perp}(K) = C_w \langle \sigma'(z)^2 \rangle_K$$

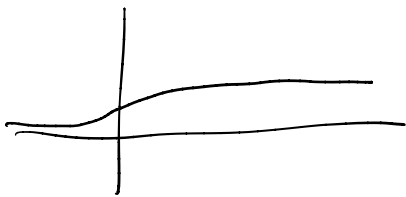
To summarize:

$$\text{criticality } \Rightarrow \begin{matrix} \chi_{11} = 1 \\ \chi_{\perp} = 1 \end{matrix} \Rightarrow \frac{\chi_{\perp}}{\chi_{11}} = 1, \text{ solve for } C_b \text{ and } C_w$$

$$\left[\begin{array}{c} 2K^2 \langle \sigma'(z)^2 \rangle_K \\ \langle \sigma(z)^2 (z^2 - K) \rangle_K \end{array} \right]_{K=K^*} = 1, \quad \begin{aligned} C_w &= \frac{1}{\langle \sigma'(z)^2 \rangle_{K^*}} \\ C_b &= K^* - \frac{\langle \sigma(z)^2 \rangle_{K^*}}{\langle \sigma'(z)^2 \rangle_{K^*}} \end{aligned}$$

Note: not every activation function has a consistent solution!

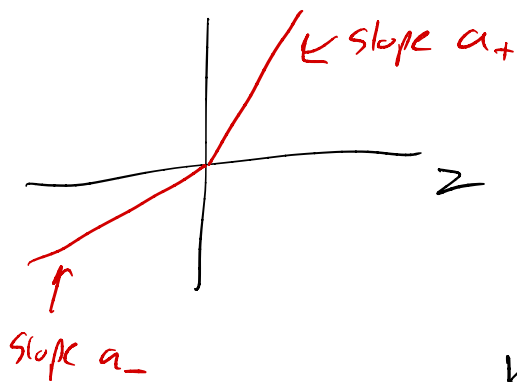
$$\text{e.g. } \sigma(z) = \frac{1}{1+e^{-z}}$$



Used historically... but criticality implies $C_b = -\left(\frac{\sigma(z)}{\sigma'(z)^2}\right) < 0$ and a negative variance is unphysical. The problem is $\sigma(0) \neq 0$!

The criticality equations can be solved numerically, or by inspection. Different values of K^* correspond to different universality classes.

- Scale-invariant (i.e. piecewise-linear w/ $\sigma(0)=0$)



$$\Rightarrow K^* = \frac{2}{a_+^2 + a_-^2} \left[\frac{1}{\lambda} \vec{x} \cdot \vec{x} \right]$$

When $C_b = 0$ and $C_w = \frac{2}{a_+^2 + a_-^2}$,

K^* is constant as a function of depth: a line of nontrivial fixed points corresponding to different input norms.

Linear activation has $a_+ = a_- = 1 \Rightarrow C_w = 1$, as we found before.

ReLU has $a_- = 0, a_+ = 1 \Rightarrow C_w = 2$, to compensate for the fact that $\max(0, z)$ knocks out half the activations on average.

- $K^* = 0$: consider a smooth activation function

$$\sigma(z) = \sum_{p=0}^{\infty} \frac{\sigma_p}{p!} z^p$$

$$\Rightarrow \langle \sigma^2(z) \rangle_K = \sigma_0^2 + (\sigma_1^2 + 2\sigma_0\sigma_2)K + \mathcal{O}(K^2)$$

$$\Rightarrow K^* = C_b + C_w \langle \sigma^2 \rangle_{K^*} \text{ has a solution, } K^* = 0, \text{ iff } \sigma_0 = 0 \text{ and } C_b = 0$$

Linearizing $\mathcal{X}_{||}$ and \mathcal{X}_{\perp} about $z=0$ and expanding in K , we find $C_w = \frac{1}{\sigma_1^2}$. For $\sigma(z) = \tanh z$, $\sigma_1 = 1$, and $C_w = 1$.

In the $K^* = 0$ universality class, K decays to 0, but only like a power law. Linearizing the recursions gives $K^{(l)} = \frac{1}{2l}$ for \tanh (and $\# \times \frac{1}{l}$ for other activations), up to $\mathcal{O}(\frac{1}{l^2})$ corrections. In other words, K is marginally irrelevant.

Fluctuations

Using the same techniques as before, we can derive recursions for the 4-point correlator. Non-Gaussianity comes from both $E[(\hat{G} - G)^2]$ and $\det(2\pi \hat{G})$, this is a long calculation.

For a single input, let's call the coefficient of the Wick tensor structure V (meant to remind us of a 4-point vertex).

Recursion is $V^{(l)} = \kappa_{11}^2(K^{(l)}) V^{(l)} + C_w^2 [\langle \sigma^4 \rangle_{K^{(l)}} - \langle \sigma^2 \rangle_{K^{(l)}}^2]$

Amazingly, tuning C_w to criticality tames exponential behavior of $V^{(l)}$ too!

- Scale-invariant: $V^{(l)} = (l-1) (\#) (K^*)^2$ (marginally relevant)
- $K^* = 0$: $V^{(l)} = (\#) (\frac{1}{l})$ (marginally irrelevant)

Note that we can assign a power-counting dimension to κ .

$[K] = 2$ and $[V] = 4$, so the dimensionless correlator is

$\frac{V}{K^2} \overset{\leftarrow \mathcal{O}(\frac{1}{l})}{\sim} \frac{1}{l}$ for both universality classes!

This is the same linear growth of fluctuations we saw in a linear network, but now we know it also characterizes nonlinear networks. ↗

Caveat: with orthogonal initializations, $\frac{V}{K^2}$ is constant with l for $K^2 = 0$, but scales as $\frac{l}{n}$ for scale-invt, except linear activations which give $\frac{V}{K^2}$ constant with depth.

$\Rightarrow K^2 = 0$ is linearizing an activation function at large depths, so nonlinear networks sort of behave linearly.