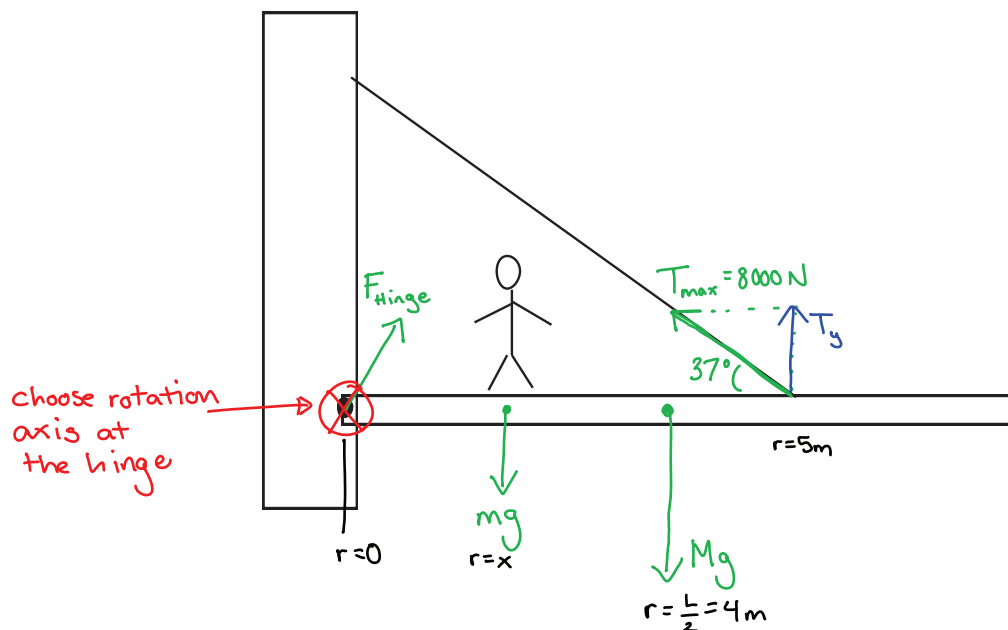


Walking the Plank

A uniform horizontal beam 8 m long is attached by a frictionless pivot to a wall. A cable making an angle of 37° , attached to the beam 5 m from the pivot point, supports the beam, which has a mass of 600 kg. The breaking point of the cable is 8000 N. A man of mass 95 kg walks out along the beam. How far can he walk before the cable breaks?



For any rotation axis we choose, it must be true that

$$\sum \vec{\tau} = \vec{\tau}_{\text{man}} + \vec{\tau}_{\text{beam}} + \vec{\tau}_{\text{wire}} + \vec{\tau}_{\text{hinge}} = 0$$

We don't know F_{hinge} , so let's make life easier by choosing a rotation axis at the hinge, as shown above.

Now, calculate torques from each force:

$$\vec{\tau}_{\text{man}} = \vec{r}_{\text{man}} \times \vec{F}_{\text{man}} = (x)(95g)(-1) = -931.95x \quad \leftarrow \text{CW torque is negative}$$

$$\vec{\tau}_{\text{beam}} = \vec{r}_{\text{beam}} \times \vec{F}_{\text{beam}} = (4)(600g)(-1) = -23544$$

$$\vec{\tau}_{\text{wire}} = \vec{r}_{\text{wire}} \times \vec{F}_{\text{wire}} = (5)(T_y)(+1) = (5)(T_{\max} \sin 37^\circ) = 24072.6$$

$$\vec{\tau}_{\text{hinge}} = \vec{r}_{\text{hinge}} \times \vec{F}_{\text{hinge}} = (0)(F_{\text{hinge}}) = 0$$

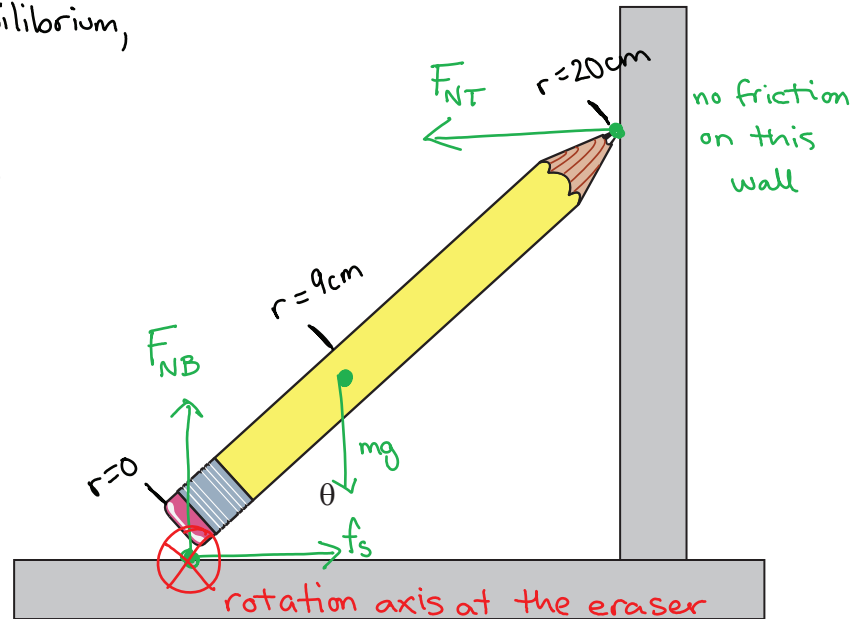
Set the sum of these torques to be equal to zero and solve to find

$$x = 0.567 \text{ m}$$

Leaning Pencil

A picture below shows a pencil with its sharpened end resting against a smooth vertical surface and its eraser end resting on the floor. The center of mass of the pencil is 9 cm from the end of the eraser and 11 cm from the tip of the lead. The coefficient of static friction between the eraser and floor is $\mu = 0.80$. What is the minimum angle θ the pencil can make with the floor such that it does not slip?

In order to be in static equilibrium, both $\sum \mathbf{F} = 0$ and $\sum \tau = 0$ must be satisfied. We will use both of these to help us solve this problem.



① $\sum F_y = 0$:

$$F_{NB} - mg = 0 \rightarrow F_{NB} = mg$$

② $\sum F_x = 0$:

$$f_s - F_{NT} = 0 \rightarrow f_s = F_{NT} = \underbrace{\mu}_{f_s \text{ is maximized}} F_{NB} = \mu mg$$

③ $\sum \tau = 0$: We'll get our easiest equation by putting the rotation axis at the eraser

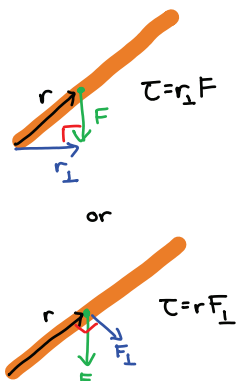
$$\sum \tau = \tau_{\text{floor}} + \tau_{\text{pencil}} + \tau_{\text{wall}} = 0$$

$$0 + (0.09 \cos \theta)(mg)(-1) + (0.2 \sin \theta)(F_{NT})(+1) = 0$$

$\downarrow F_{NT} = f_s$

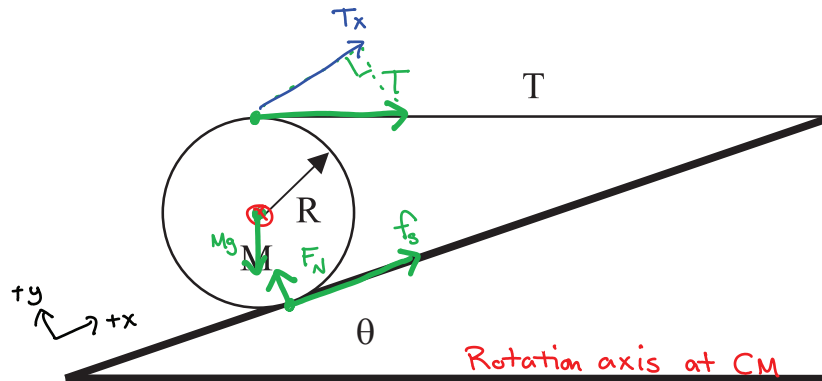
Solve the above equation to find

$$\boxed{\theta = 29.35^\circ}$$



Cylinder Held on Inclined Plane

A cylinder of mass M and radius R is in static equilibrium as shown in the diagram. The cylinder rests on an inclined plane making an angle θ with the horizontal and is held by a horizontal string attached to the top of the cylinder and to the inclined plane. There is friction between the cylinder and the plane. What is the tension in the string T ?



Once again, we'll take advantage of $\sum \tau = 0$ and $\sum \mathbf{F} = 0$:

$$\sum \tau = 0:$$

$$\begin{aligned}\sum \tau &= \tau_{\text{string}} + \tau_{\text{friction}} + \tau_{\text{normal}} + \tau_{\text{gravity}} \\ &= (R)(T)(-1) + (R)(f_s)(+1) \\ -RT + Rf_s &= 0 \rightarrow f_s = T\end{aligned}$$

$\tau_{\text{normal}} = 0$ because \vec{F}_N is parallel to \vec{r} .

$\tau_{\text{gravity}} = 0$ because $\vec{r} = 0$

$\sum F_x = 0$: Using tilted axes,

$$\begin{aligned}\sum F_x &= T \cos \theta + f_s - Mg \sin \theta \\ T \cos \theta + T - Mg \sin \theta &= 0\end{aligned}$$

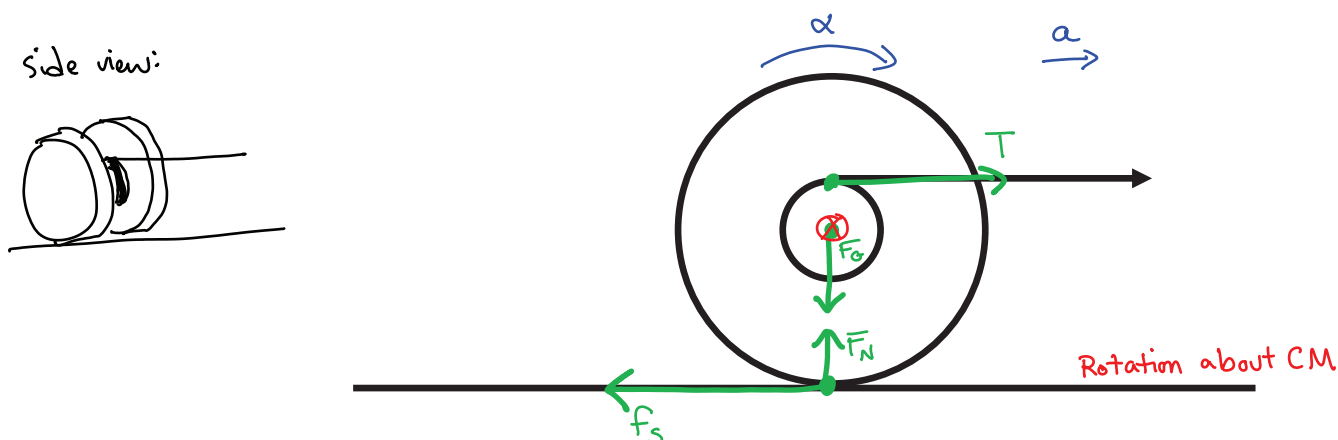
Solve for T to find

$$T = \frac{Mg \sin \theta}{1 + \cos \theta}$$

Review: Rolling Spool

A spool with outer radius R and inner radius r rolls without slipping on a horizontal surface. The inner part may be approximated as a uniform cylinder (radius r) of mass m . The two rims may be thought of as disks (of radius R) and mass M each. Total mass is $m + 2M$.

The spool is pulled by a rope of tension T wrapped around the inner radius as pictured. What is the acceleration of the center of mass of the spool?



The spool is not slipping on the floor, thus we know

- ① there is static friction at the floor (drawn above)
- ② $a_{cm} = \alpha R$ (not αr)

Using Newton's 2nd Law:

$$\sum \tau = I\alpha$$

$$\sum \tau = \tau_T + \tau_f = rT + Rf$$

$$I = I_{small} + 2I_{big} = \frac{1}{2}mr^2 + MR^2$$

So we have

$$rT + Rf = \left(\frac{1}{2}mr^2 + MR^2 \right) \left(\frac{a_{cm}}{R} \right)$$

$$\sum F_x = (m + 2M)a_{cm}$$

$$\sum F_x = T - f \rightarrow T - f = (m + 2M)a_{cm}$$

Combine the two equations to find

$$a_{cm} = \frac{T(R+r)}{3MR + mR + \frac{mr^2}{2R}}$$