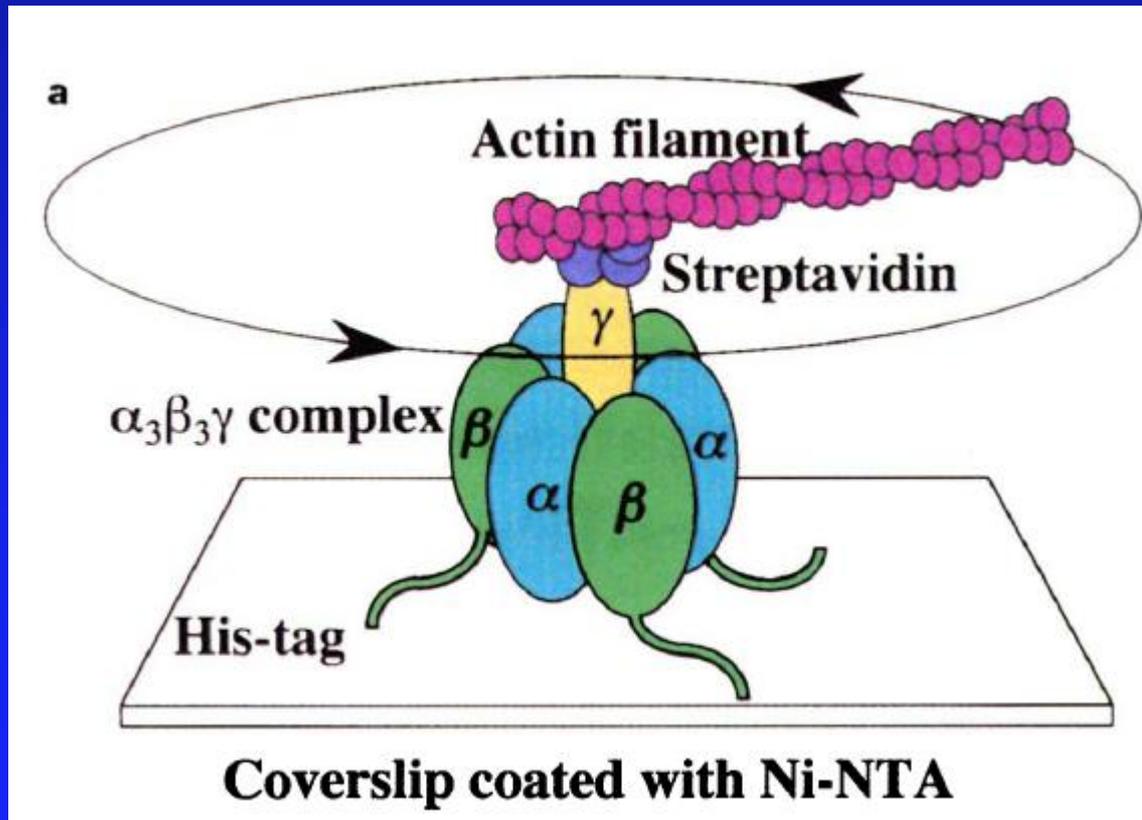
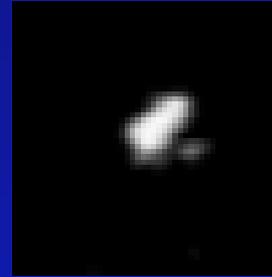


# EXAM II

## Physics 101: Lecture 13 Rotational Kinetic Energy and Rotational Inertia



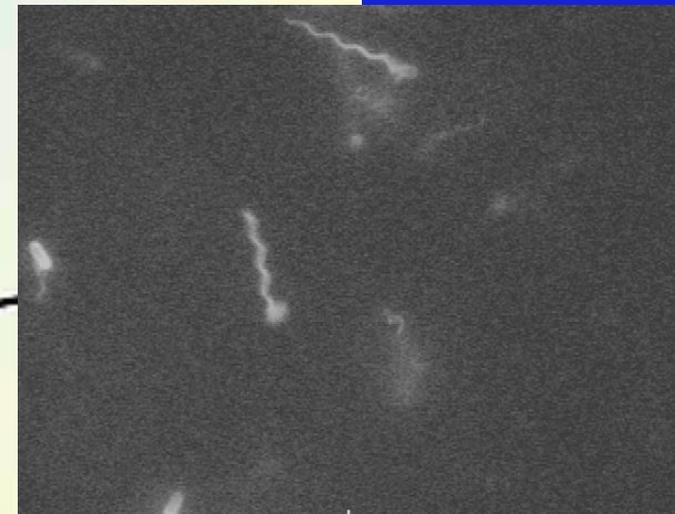
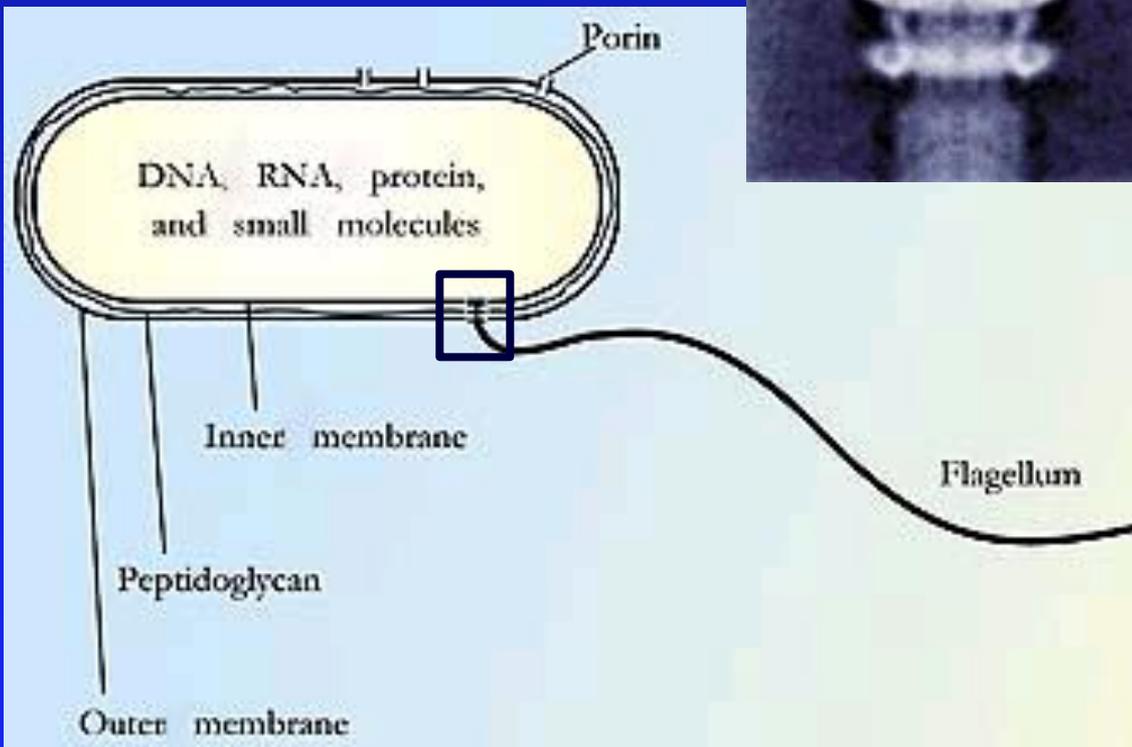
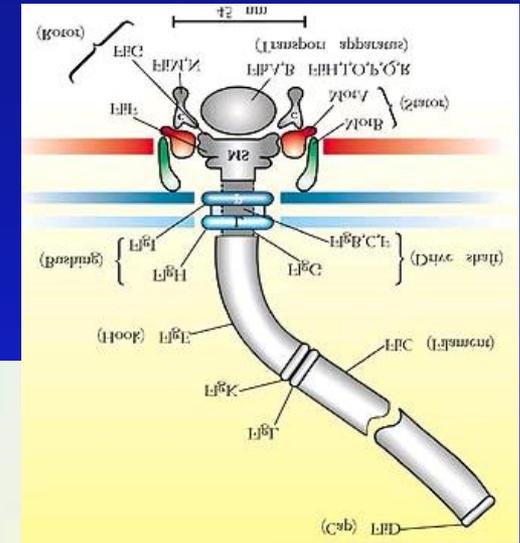
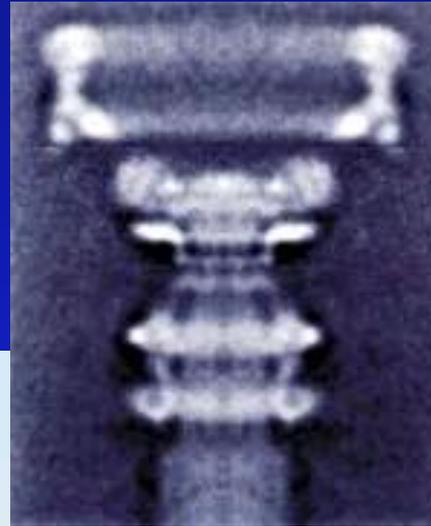
# Rotary motor in biology #1



F1-ATPase

# Rotary motor in biology #2

## Bacterial flagellum



# Overview of Semester

- Newton's Laws

- $F_{\text{Net}} = m a$

- Work-Energy

- $F_{\text{Net}} = m a$       multiply both sides by  $d$

- $W_{\text{Net}} = \Delta KE$       Energy is “conserved”

  - Useful when know Work done by forces

- Impulse-Momentum

- $F_{\text{Net}} = m a = \Delta p / \Delta t$

- Impulse =  $\Delta p$

  - Momentum is conserved

  - Works in each direction independently

# Linear and Angular Motion

	Linear	Angular
Displacement	$x$	$\theta$
Velocity	$v$	$\omega$
Acceleration	$a$	$\alpha$
Inertia	$m$	$I$
KE	$\frac{1}{2} m v^2$	Today!
Newton's 2 <sup>nd</sup>	$F=ma$	
Momentum	$p = mv$	

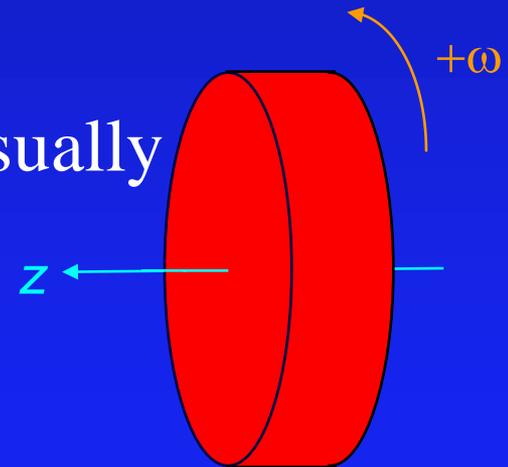
# Comment on axes and sign (i.e. what is positive and negative)

Whenever we talk about rotation, it is implied that there is a rotation “axis”.

This is usually called the “z” axis (we usually omit the z subscript for simplicity).

**Counter-clockwise** (increasing  $\theta$ ) is usually called positive.

**Clockwise** (decreasing  $\theta$ ) is usually called **negative**. [demo]



# Energy ACT/demo

- When the bucket reaches the bottom, its potential energy has decreased by an amount  $mgh$ . Where has this energy gone?

- A) Kinetic Energy of bucket
- B) Kinetic Energy of flywheel
- C) Both 1 and 2.

At bottom, bucket has zero velocity, energy must be in flywheel!



# Rotational Kinetic Energy

- Consider a mass  $M$  on the end of a string being spun around in a circle with radius  $r$  and angular frequency  $\omega$  [demo]

→ Mass has speed  $v = \omega r$

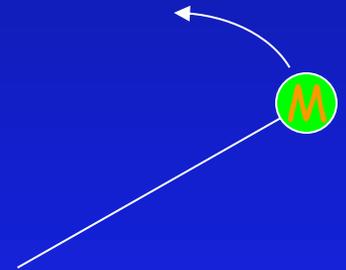
→ Mass has kinetic energy

»  $K = \frac{1}{2} M v^2$

»  $= \frac{1}{2} M \omega^2 r^2$

»  $= \frac{1}{2} (M r^2) \omega^2$

»  $= \frac{1}{2} I \omega^2$



- **Rotational Kinetic Energy** is energy due to circular motion of object.

# Rotational Inertia I

- Tells how much “work” is required to get object spinning. Just like mass tells you how much “work” is required to get object moving.
  - $K_{\text{tran}} = \frac{1}{2} m v^2$  Linear Motion
  - $K_{\text{rot}} = \frac{1}{2} I \omega^2$  Rotational Motion
- $I = \sum m_i r_i^2$  (units  $\text{kg m}^2$ )
- **Note!** Rotational Inertia (or “Moment of Inertia”) depends on what you are spinning about (basically the  $r_i$  in the equation).

# Rotational Inertia Table

- For objects with finite number of masses, use  $I = \sum m r^2$ . For “continuous” objects, use table below (p. 263 of book).

Copyright © The McGraw-Hill Companies, Inc. Permission required for reproduction or display.

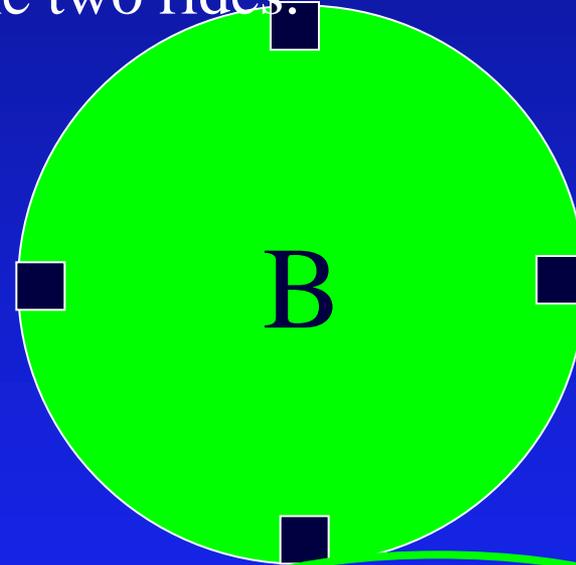
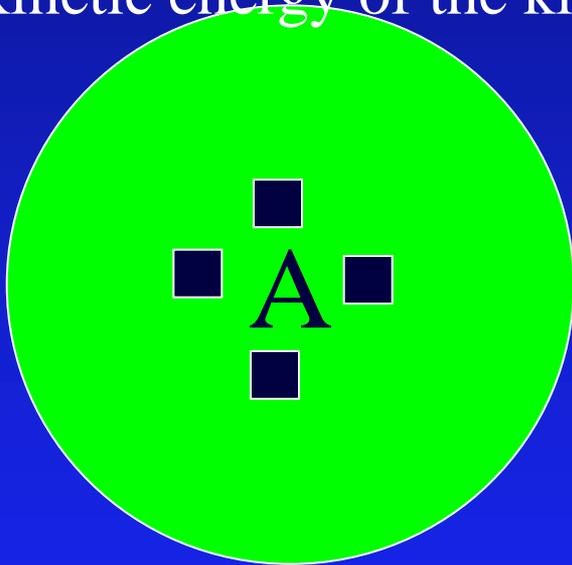
**Table 8.1**

**Rotational Inertia for Uniform Objects with Various Geometrical Shapes**

Shape	Axis of Rotation	Rotational Inertia	Shape	Axis of Rotation	Rotational Inertia
Thin hollow cylindrical shell (or hoop)	Central axis of cylinder	$MR^2$	Solid sphere	Through center	$\frac{2}{5}MR^2$
Solid cylinder (or disk)	Central axis of cylinder	$\frac{1}{2}MR^2$	Thin hollow spherical shell	Through center	$\frac{2}{3}MR^2$
Hollow cylindrical shell or disk	Central axis of cylinder	$\frac{1}{2}M(a^2 + b^2)$	Thin rod	Perpendicular to rod through end	$\frac{1}{3}ML^2$
			Rectangular plate	Perpendicular to plate through center	$\frac{1}{12}M(a^2 + b^2)$

# Merry Go Round

Four kids (mass  $m$ ) are riding on a (light) merry-go-round rotating with angular velocity  $\omega=3$  rad/s. In case A the kids are near the center ( $r=1.5$  m), in case B they are near the edge ( $r=3$  m). Compare the kinetic energy of the kids on the two rides.



A)  $K_A > K_B$

B)  $K_A = K_B$

C)  $K_A < K_B$

$$KE = 4 \times \frac{1}{2} m v^2$$

$$= 4 \times \frac{1}{2} m \omega r^2 = \frac{1}{2} I \omega^2 \quad \text{Where } I = 4 m r^2$$

Further mass is from axis of rotation, greater KE it has.

[strength contest]

# Inertia Rods

Two batons have equal mass and length.  
Which will be “easier” to spin

A) Mass on ends



B) Same

C) Mass in center



$I = \sum m r^2$  Further mass is from axis of rotation,  
greater moment of inertia (harder to spin)

# Prelecture: Rolling Race (Hoop vs Cylinder)

A solid and hollow cylinder of equal mass roll down a ramp with height  $h$ . Which has greatest KE at bottom?

A) Solid

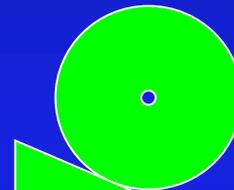
25%

B) Hollow

20%

C) Same

54%



"Both start with same PE so they both end with same KE."

# Prelecture: Rolling Race (Hoop vs Cylinder)

A solid and hollow cylinder of equal mass roll down a ramp with height  $h$ . Which has greatest speed at the bottom of the ramp?

A) Solid

50%

B) Hollow

17%

C) Same

33%



$$I = MR^2$$



$$I = \frac{1}{2} MR^2$$

# Main Ideas

- Rotating objects have kinetic energy
  - $KE = \frac{1}{2} I \omega^2$
- Moment of Inertia  $I = \Sigma mr^2$ 
  - Depends on Mass
  - Depends on axis of rotation
- Energy is conserved but need to include rotational energy too:  $K_{rot} = \frac{1}{2} I \omega^2$

# Massless Pulley Example

Consider the two masses connected by a pulley as shown. Use conservation of energy to calculate the speed of the blocks after  $m_2$  has dropped a distance  $h$ . Assume the pulley is massless.

$$E = K + U$$

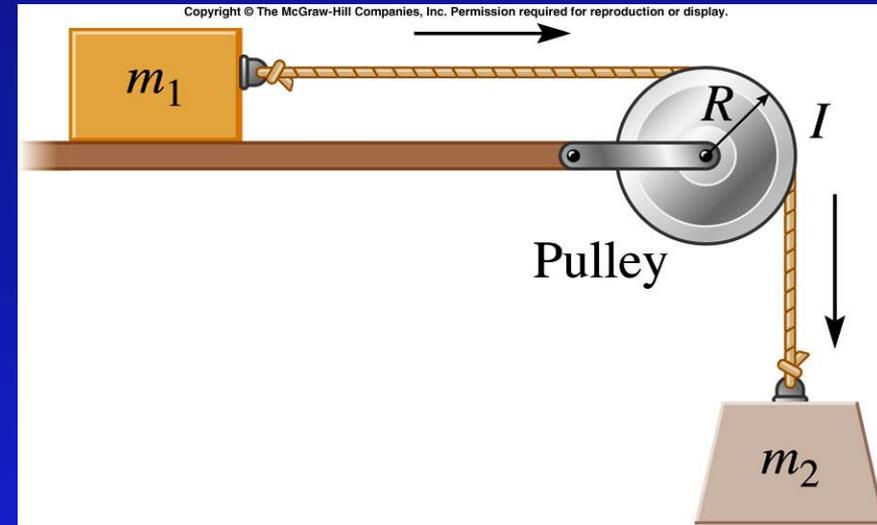
$$E_0 = E_f$$

$$U_{initial} + K_{initial} = U_{final} + K_{final}$$

$$0 + 0 = -m_2gh + \frac{1}{2}m_1v^2 + \frac{1}{2}m_2v^2$$

$$2m_2gh = m_1v^2 + m_2v^2$$

$$v = \sqrt{\frac{2m_2gh}{m_1 + m_2}}$$

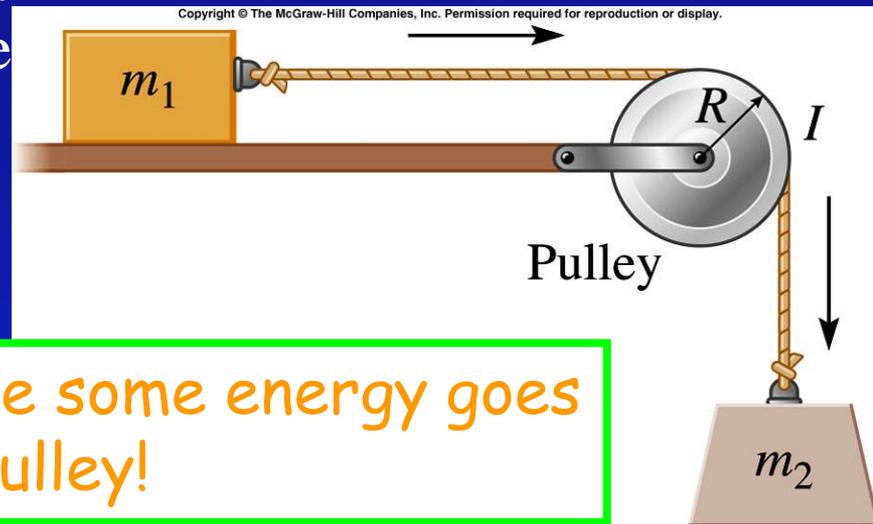


Note: Tension does positive work on 1 and negative work on 2. Net work (on 1 and 2) by tension is ZERO.

# Massive Pulley Act

Consider the two masses connected by a pulley as shown. If the pulley is massive after  $m_2$  drops a distance  $h$ , the blocks will be moving

- A) faster than
  - B) the same speed as
  - C) slower than
- if it was a massless pulley



Slower because some energy goes into spinning pulley!

$$U_{initial} + K_{initial} = U_{final} + K_{final}$$

$$m_2gh = +\frac{1}{2}m_1v^2 + \frac{1}{2}m_2v^2 + \frac{1}{4}Mv^2$$

$$0 = -m_2gh + \frac{1}{2}m_1v^2 + \frac{1}{2}m_2v^2 + \frac{1}{2}I\omega^2$$

$$v = \sqrt{\frac{2m_2gh}{m_1 + m_2 + M/2}}$$

$$m_2gh = +\frac{1}{2}m_1v^2 + \frac{1}{2}m_2v^2 + \frac{1}{2}\left(\frac{1}{2}MR^2\right)\left(\frac{v}{R}\right)^2$$

# Summary

- Rotational Kinetic Energy  $K_{\text{rot}} = \frac{1}{2} I \omega^2$
- Rotational Inertia  $I = \sum m_i r_i^2$
- Energy Still Conserved!