

Leveraging Physics for Security: Micro-PMUs

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CYBER RESILIENT ENERGY
DELIVERY CONSORTIUM

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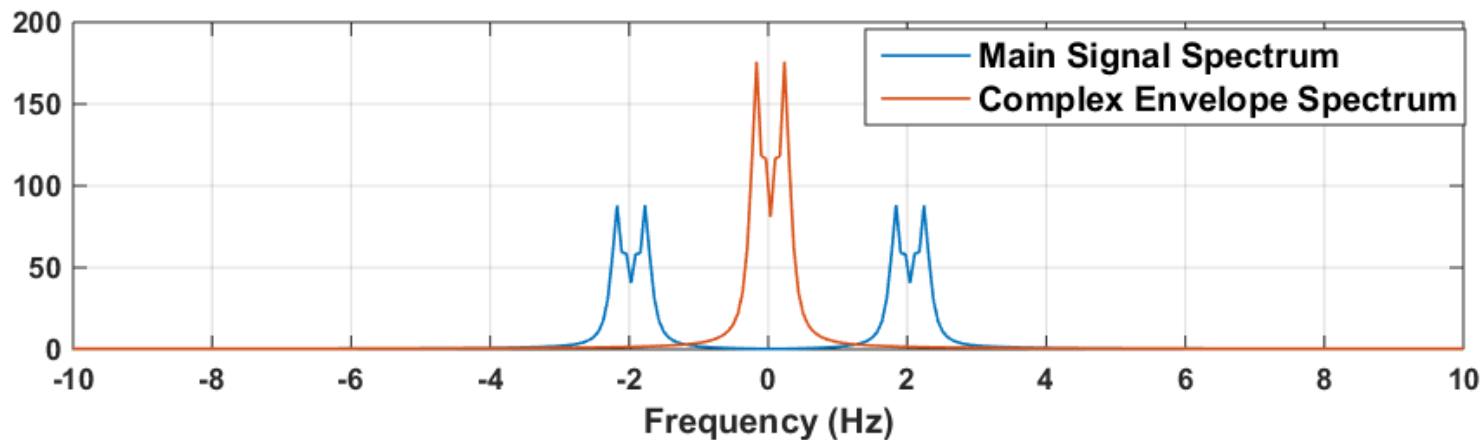
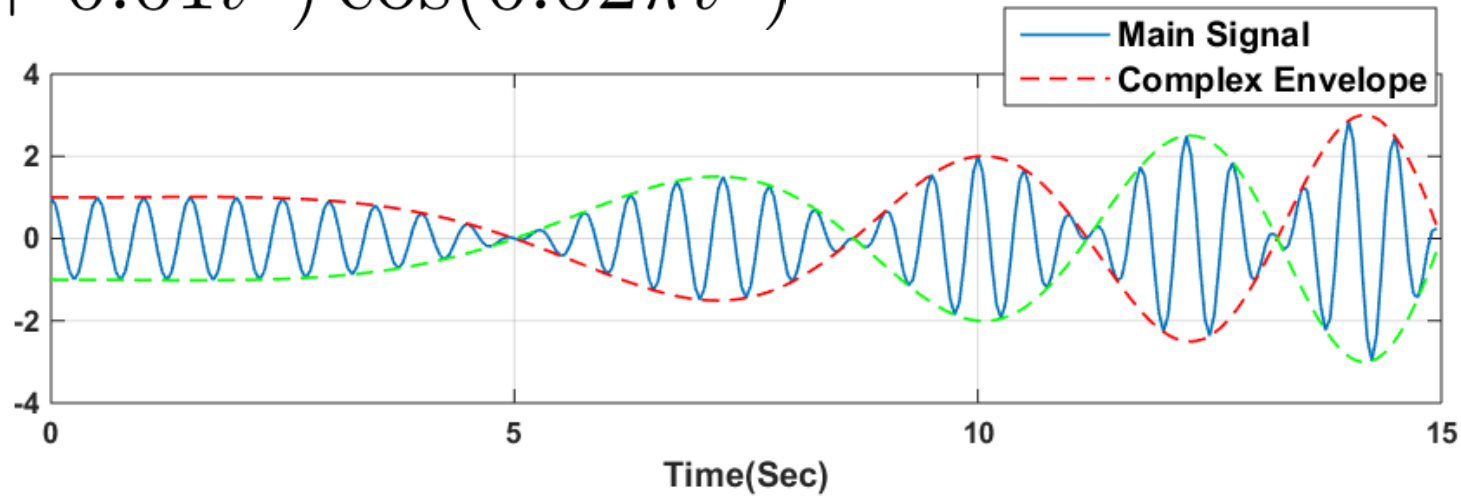
Example 1

Real signal (e.g. AC voltage, AC current)

$$s(t) = (1 + 0.01t^2) \cos(0.02\pi t^2) \cos(4\pi t)$$

Phasor signal

$$\tilde{s}(t) = (1 + 0.01t^2) \cos(0.02\pi t^2)$$



Example 2

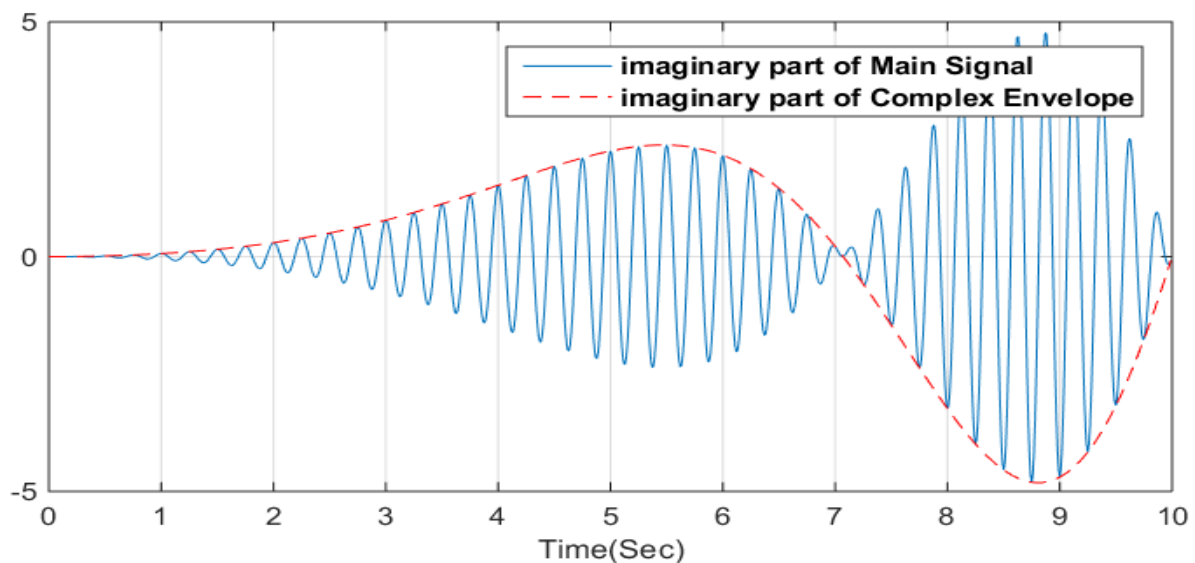
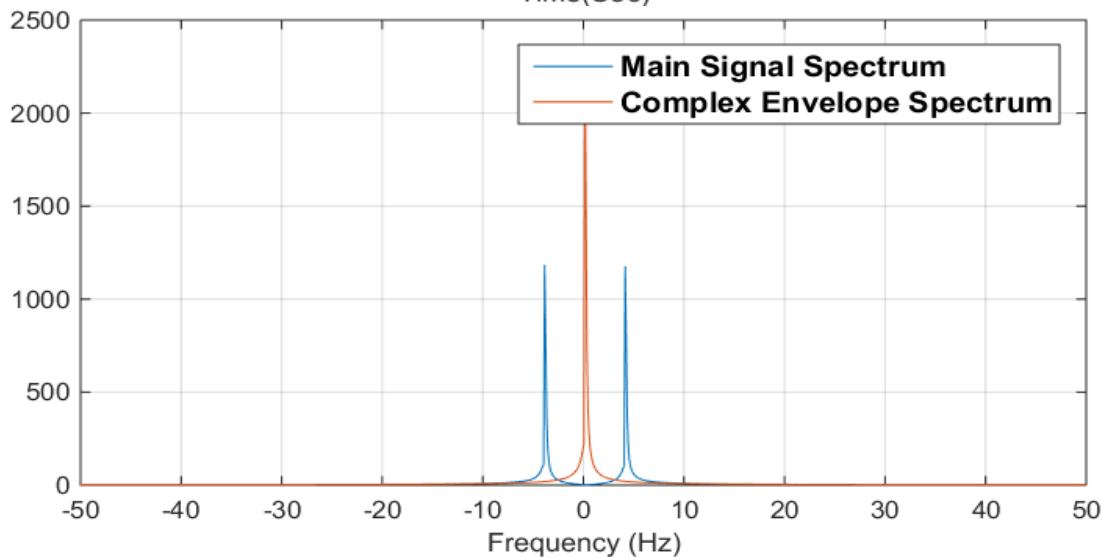
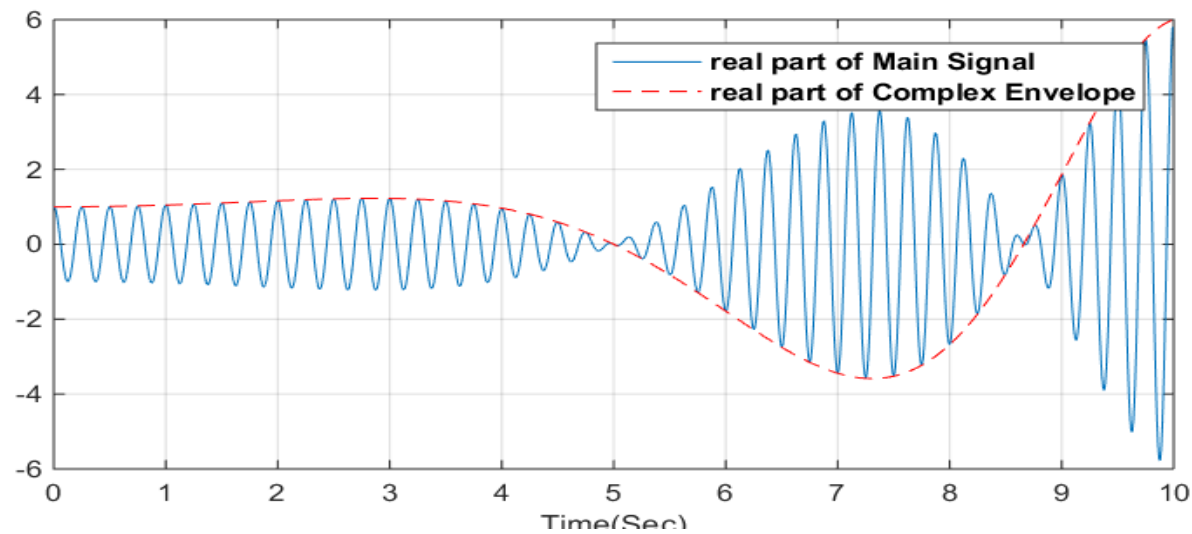
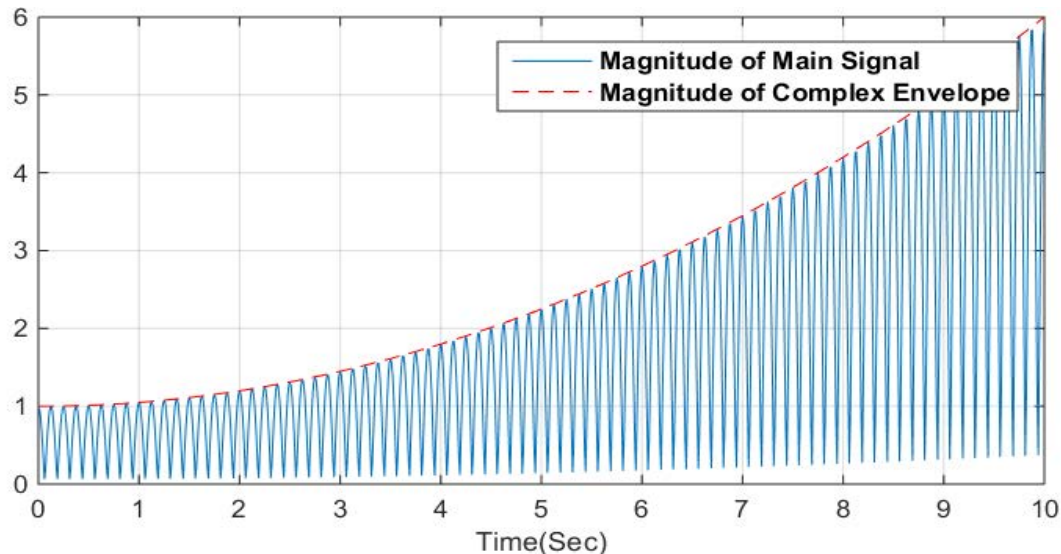
Complex signal

$$s(t) = (1 + 0.05t^2)e^{j0.1\pi t^2} \cos(8\pi t)$$



Phasor signal

$$\tilde{s}(t) = (1 + 0.05t^2)e^{j0.1\pi t^2}$$



Phasor (Complex Envelope)

- Complex envelope: baseband representation of the band-pass signals.

– In Theory:

$$s(t) \xrightarrow{1} s^+(t) = \frac{1}{2}s(t) + \frac{j}{2\pi t} \star s(t) \xrightarrow{2} \tilde{s}(t) = \sqrt{2}s^+(t)e^{-j2\pi f_0 t}.$$

analytic signal complex envelope
shift and scale

$s(t)$ is bandpass

– In practice:

W : frequency support of the signal

f_0 : signal center frequency

Assume that $\frac{W}{2} \leq f_0$

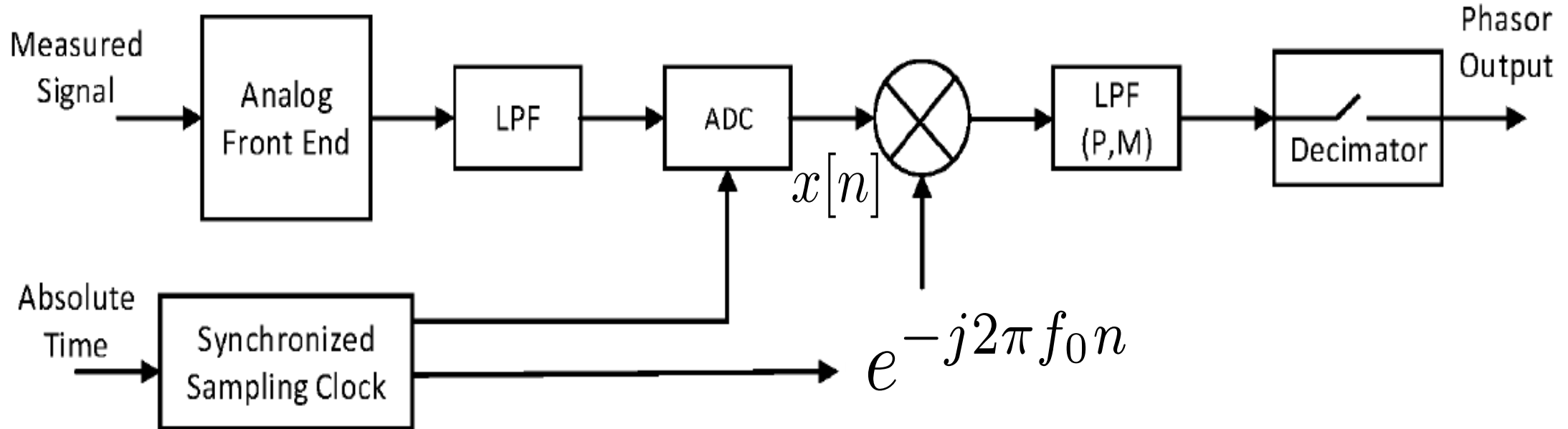
$$s(t) \xrightarrow{1} \tilde{s}(t) = \sqrt{2}(s(t)e^{-j2\pi f_0 t}) \star h(t)$$

$h(t)$: low-pass filter

Note : $\tilde{s}(t)$ is band-limited \longrightarrow can be sampled at $2f_0$ Hz.

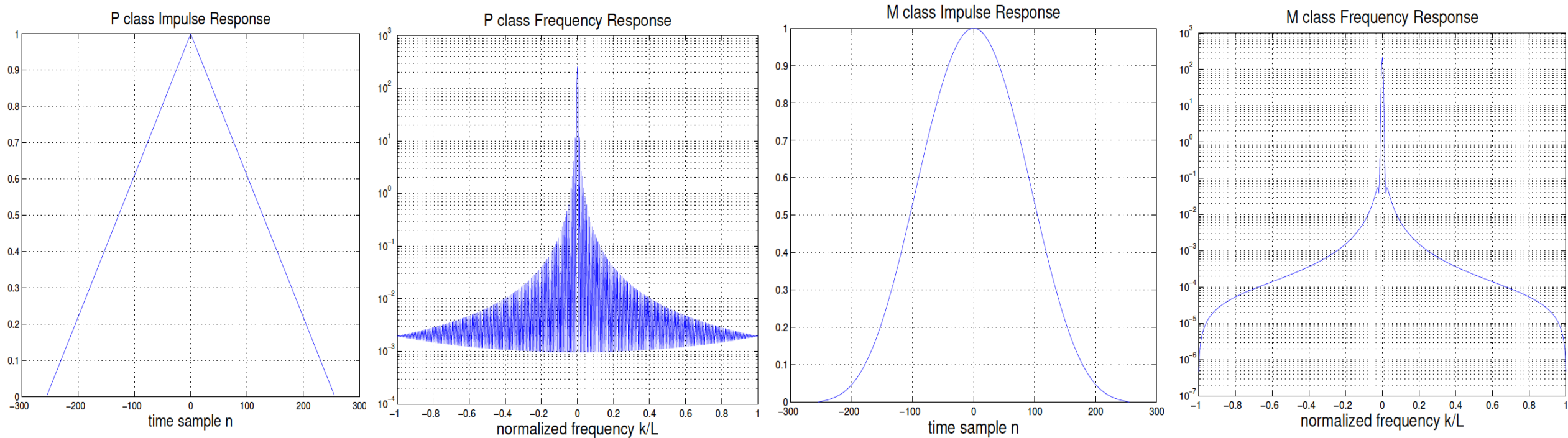
Micro-Phasor Measurement Units (μ PMUs)

- Voltage and current in power system are (band-limited) bandpass signals.
- μ PMUs are low-cost and small synchrophasor devices that sample voltage and current with $512 \cdot 60$ Hz rate and extract the **complex envelope** with 120 Hz.



$$\mu\text{PMU output: } \mathbf{v}[k] \in \mathbb{C}^{3 \times 1}, \quad \mathbf{i}[k] \in \mathbb{C}^{3 \times 1}$$

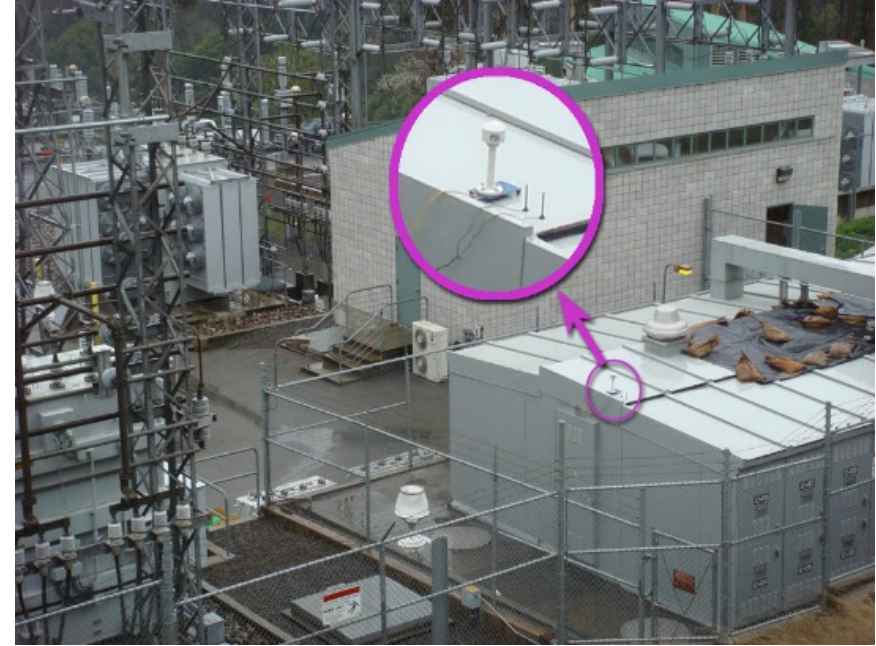
- IEEE C.37 standard filters: P class and M class.
- P class and M class differ because they have two different responses for the Low Pass Filter (LPF). P has high side-lobes \rightarrow more sensitive to noise but also to transients.



- μ PMUs have proprietary filters to handle the different distribution grid environment as opposed to the transmission

0.002° resolution, 0.0002% magnitude, 0.01% Total Vector Error (TVE)!

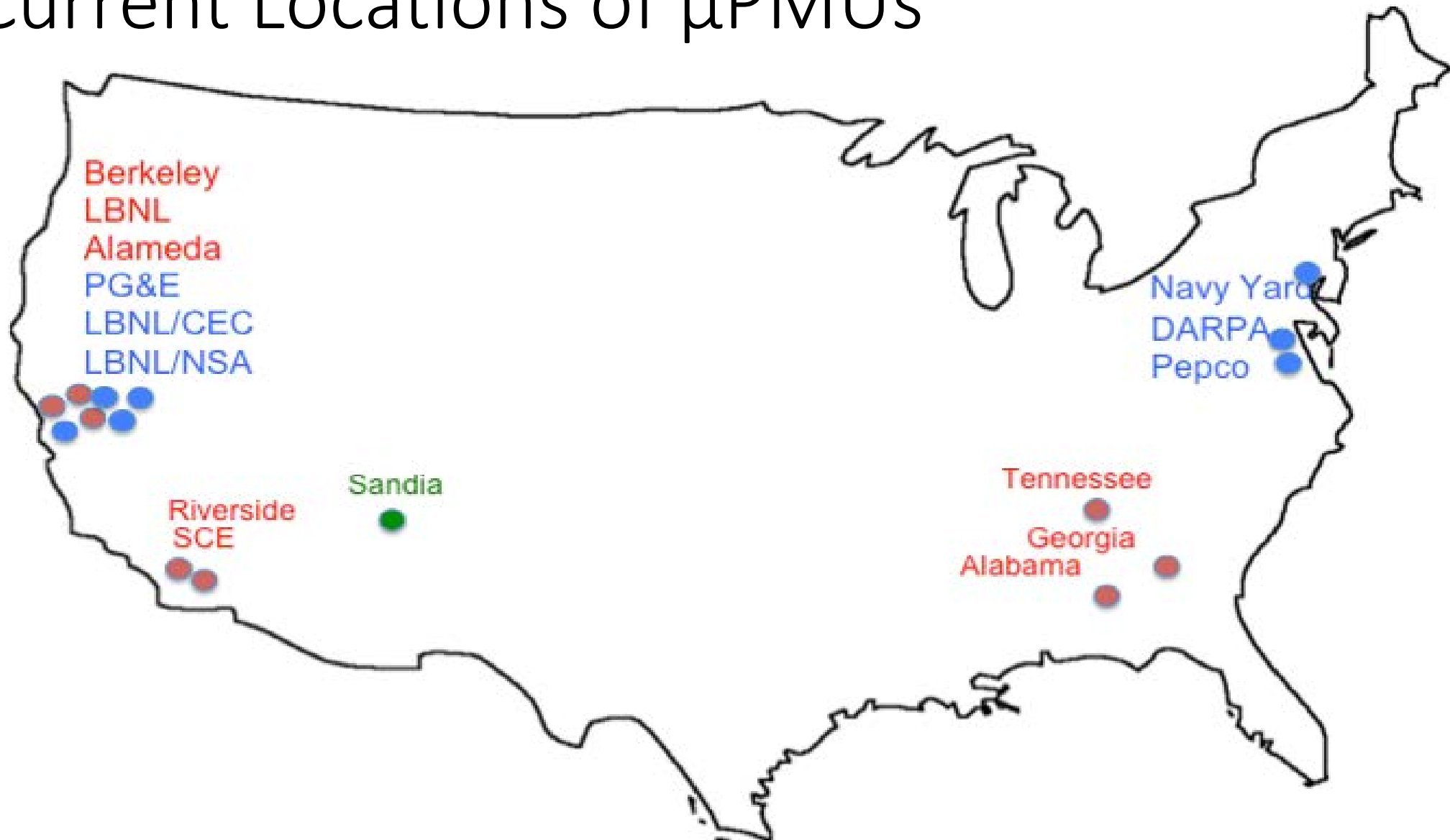
Micro-Phasor Measurement Units (Cntd.)



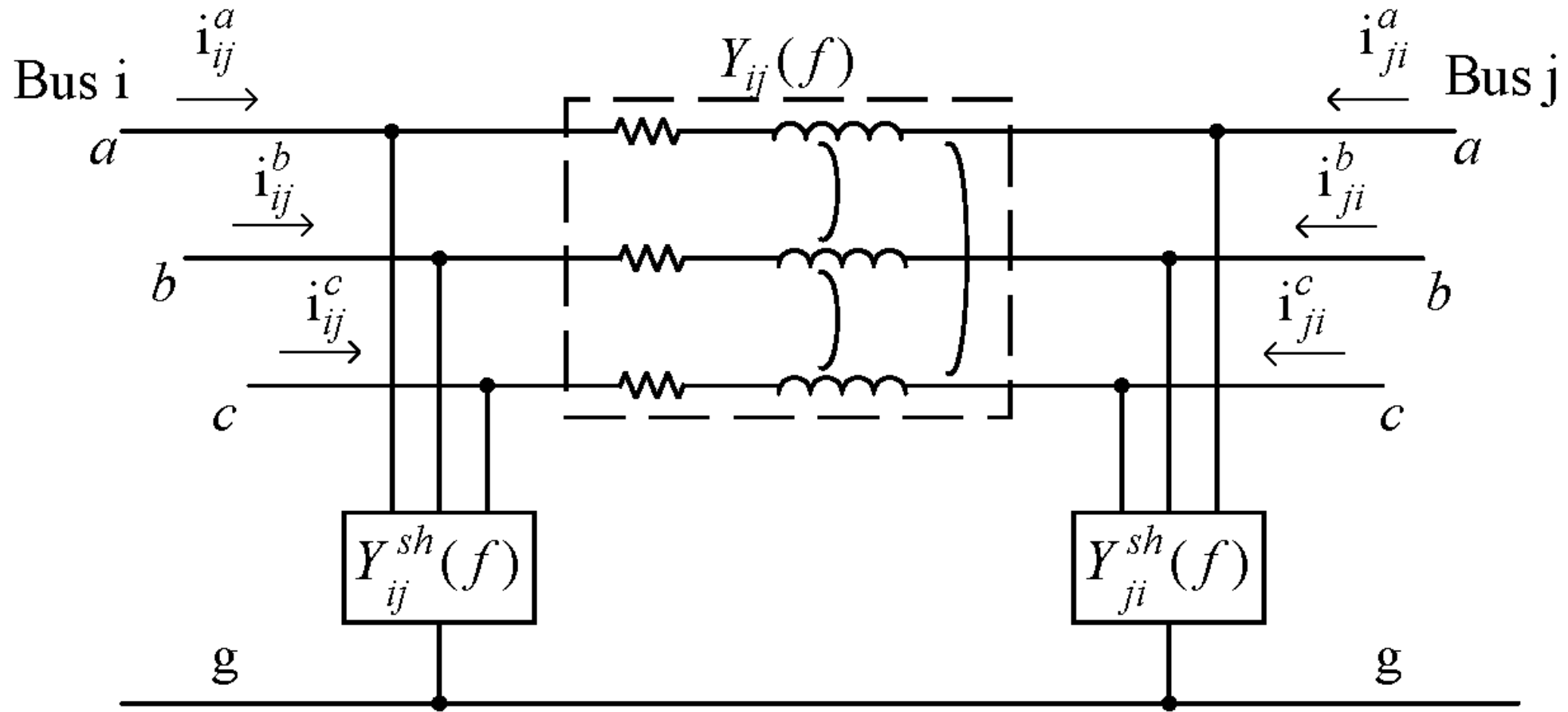
Installation at Grizzly Substation, Lawrence Berkeley National Lab, highlighting GPS and modem antennae.

- Sample Measurements: <http://mobile.pqube3.com/> <https://plot2.upmu.org/>
- Designed for harsh distribution grid environment: <http://PQube3.com/tough>

Current Locations of μ PMUs



Distribution Line Model



- Linear Time Invariant (LTI) system \rightarrow Multi-Input Multi-Output (MIMO) representation also holds for the complex envelopes.

Distribution Line Model (cntd.)

$$\mathbf{i}_{ij}(f) = (\mathbf{y}_{ij}^{sh}(f) + \mathbf{y}_{ij}(f))\mathbf{v}_i(f) - \mathbf{y}_{ij}(f)\mathbf{v}_j(f)$$

$$\mathbf{i}_{ij}(t) = (\mathbf{y}_{ij}^{sh}(t) + \mathbf{y}_{ij}(t)) * \mathbf{v}_i(t) - \mathbf{y}_{ij}(t) * \mathbf{v}_j(t)$$

$\mathbf{y}_{ij}^{sh}(t)$: line shunt parameter impulse response $\mathbf{y}_{ij}(t)$: line series parameter impulse response

$$\mathbf{y}_{ij}^{sh}(f) \triangleq \mathbf{Y}_{ij}^{sh}(f + f_0), \mathbf{y}_{ij}(f) \triangleq \mathbf{Y}_{ij}(f + f_0)$$

$$\bar{\mathbf{Y}}_{ij}(f) \triangleq \mathbf{Y}_{ij}^{sh}(f) + \mathbf{Y}_{ij}(f)$$

$$\bar{\mathbf{y}}_{ij}(f) \triangleq \mathbf{y}_{ij}^{sh}(f) + \mathbf{y}_{ij}(f)$$

$$\bar{\mathbf{y}}_{ij}(t) \triangleq \mathbf{y}_{ij}^{sh}(t) + \mathbf{y}_{ij}(t)$$



$$\mathbf{i}_{ij}(f) = \bar{\mathbf{y}}_{ij}(f)\mathbf{v}_i(f) - \mathbf{y}_{ij}(f)\mathbf{v}_j(f)$$

$$\mathbf{i}_{ij}(t) = \bar{\mathbf{y}}_{ij}(t) * \mathbf{v}_i(t) - \mathbf{y}_{ij}(t) * \mathbf{v}_j(t)$$

In discrete time:

$$\mathbf{i}_{ij}[k] = \sum_{n=0}^{N-1} \bar{\mathbf{y}}_{ij}[n]\mathbf{v}_i[k-n] - \sum_{n=0}^{N-1} \mathbf{y}_{ij}[n]\mathbf{v}_j[k-n]$$

we assumed that $\mathbf{y}_{ij}^{sh}[n]$ and $\mathbf{y}_{ij}[n]$ are the samples respectively of $\mathbf{y}_{ij}^{sh}(t) \star h(t)$ and $\mathbf{y}_{ij}(t) \star h(t)$ and that they have finite support N , and are causal.

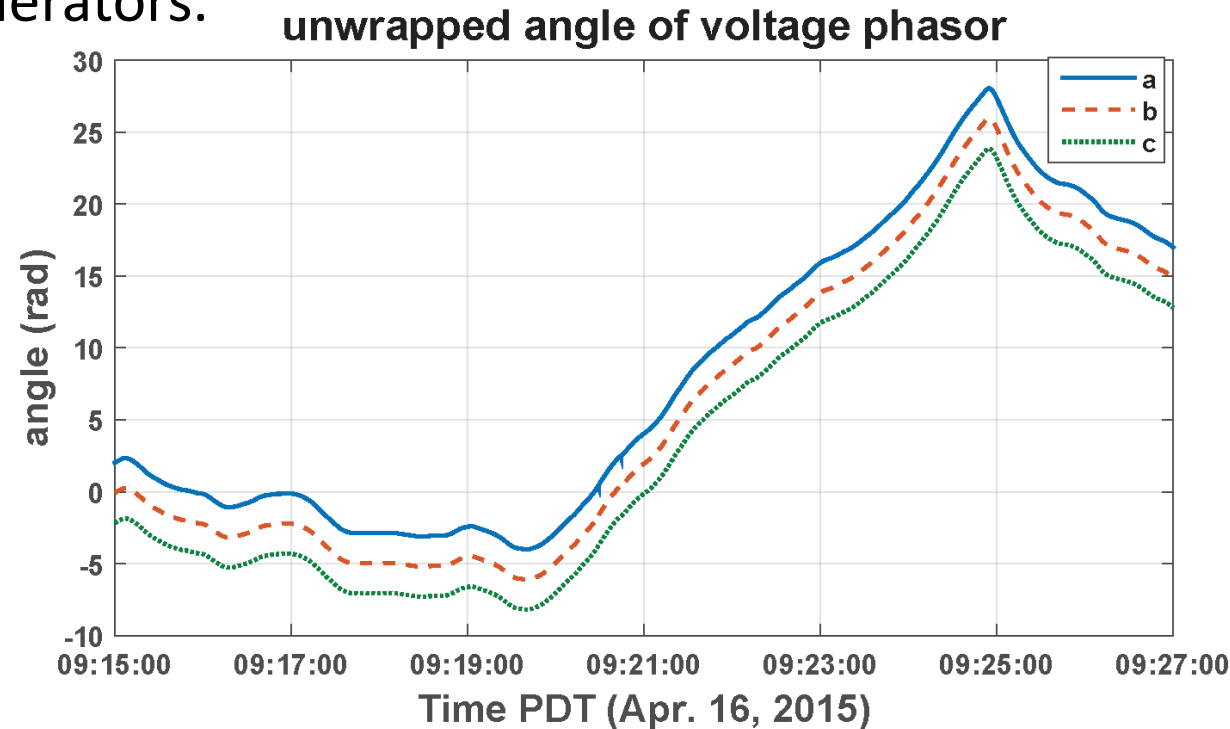
Line Model (Quasi steady-state)

- Steady-state never happens in reality [1]
 1. load-generation imbalances.
 2. active power demand interactions.
 3. large generators inertia.
 4. automatic speed controllers of the generators.

What is the effect on μ PMU output??

$$\mathbf{v}_i[k] = \hat{\mathbf{v}}_i[k] e^{j\beta_k k}, \quad \mathbf{i}_{ij}[k] = \hat{\mathbf{i}}_{ij}[k] e^{j\beta_k k}$$

β_k is the drift in the frequency.



Line Model (Quasi steady-state cntd.)

Main assumption: $\hat{\mathbf{v}}_i[k-n] \approx \hat{\mathbf{v}}_i[k]$ and $\beta_{k-n} \approx \beta_k$ for $n = 0, \dots, N-1$

→
$$\mathbf{i}_{ij}[k] \approx \left(\sum_{n=0}^{N-1} \bar{\mathbf{y}}_{ij}[n] e^{-j\beta_k n} \right) \mathbf{v}_i[k] - \left(\sum_{n=0}^{N-1} \mathbf{y}_{ij}[n] e^{-j\beta_k n} \right) \mathbf{v}_j[k]$$

$$\bar{\mathbf{Y}}_{ij}(f_0, \beta_k) \triangleq T \bar{\mathbf{Y}}_{ij} \left(f_0 + \frac{\beta_k}{2\pi T} \right) H \left(\frac{\beta_k}{2\pi T} \right);$$

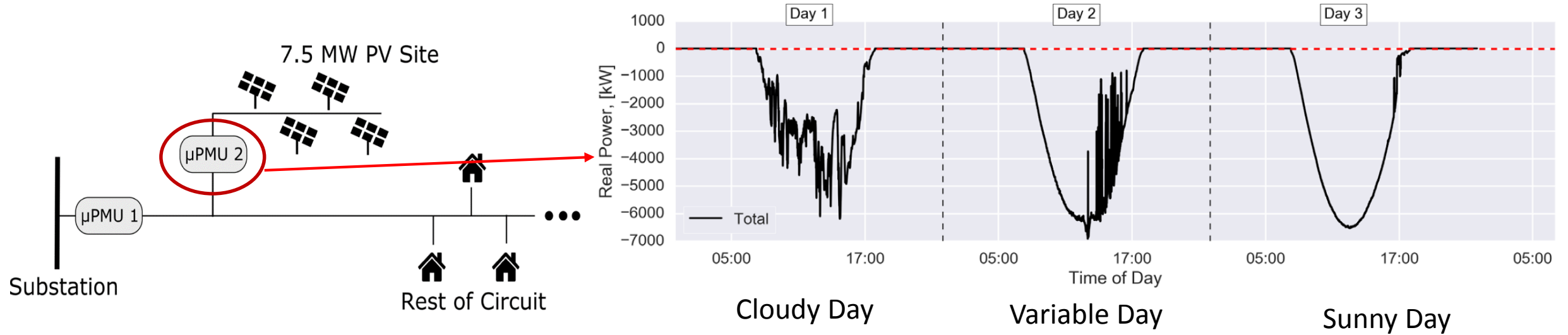
$$\mathbf{Y}_{ij}(f_0, \beta_k) \triangleq T \mathbf{Y}_{ij} \left(f_0 + \frac{\beta_k}{2\pi T} \right) H \left(\frac{\beta_k}{2\pi T} \right);$$

$$\mathbf{i}_{ij}[k] = \bar{\mathbf{Y}}_{ij}(f_0, \beta_k) \mathbf{v}_i[k] - \mathbf{Y}_{ij}(f_0, \beta_k) \mathbf{v}_j[k]$$

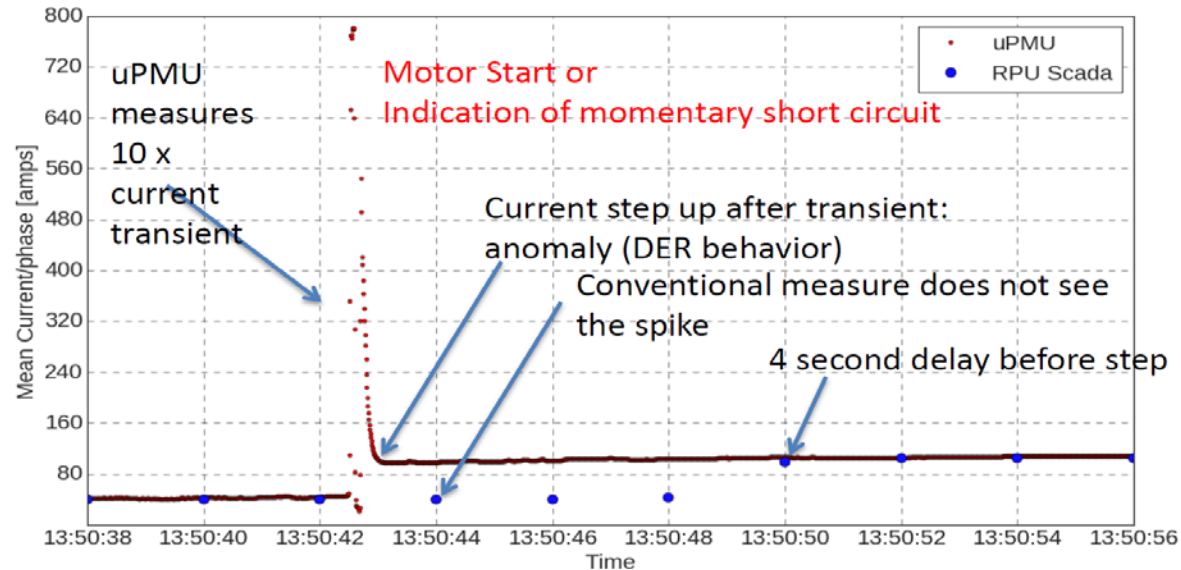
modulated admittance parameters.

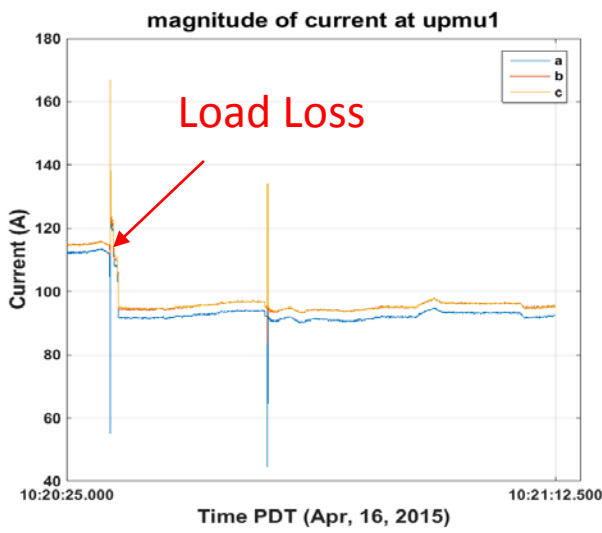
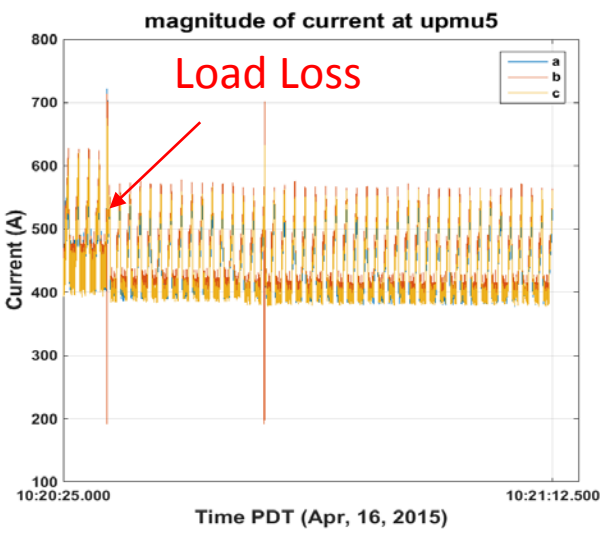
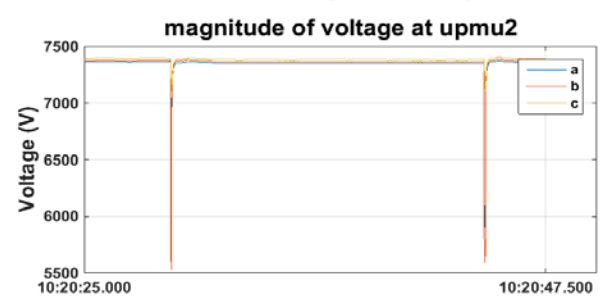
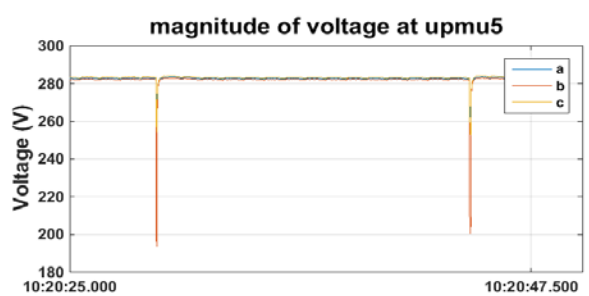
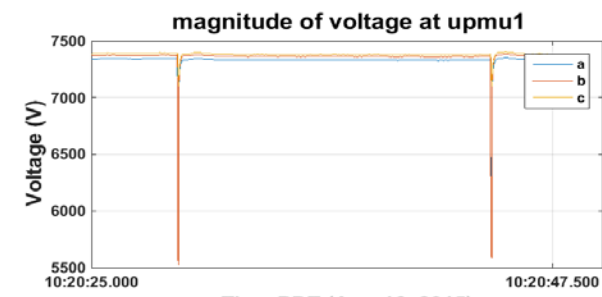
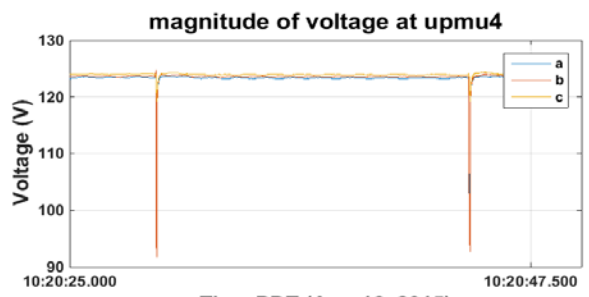
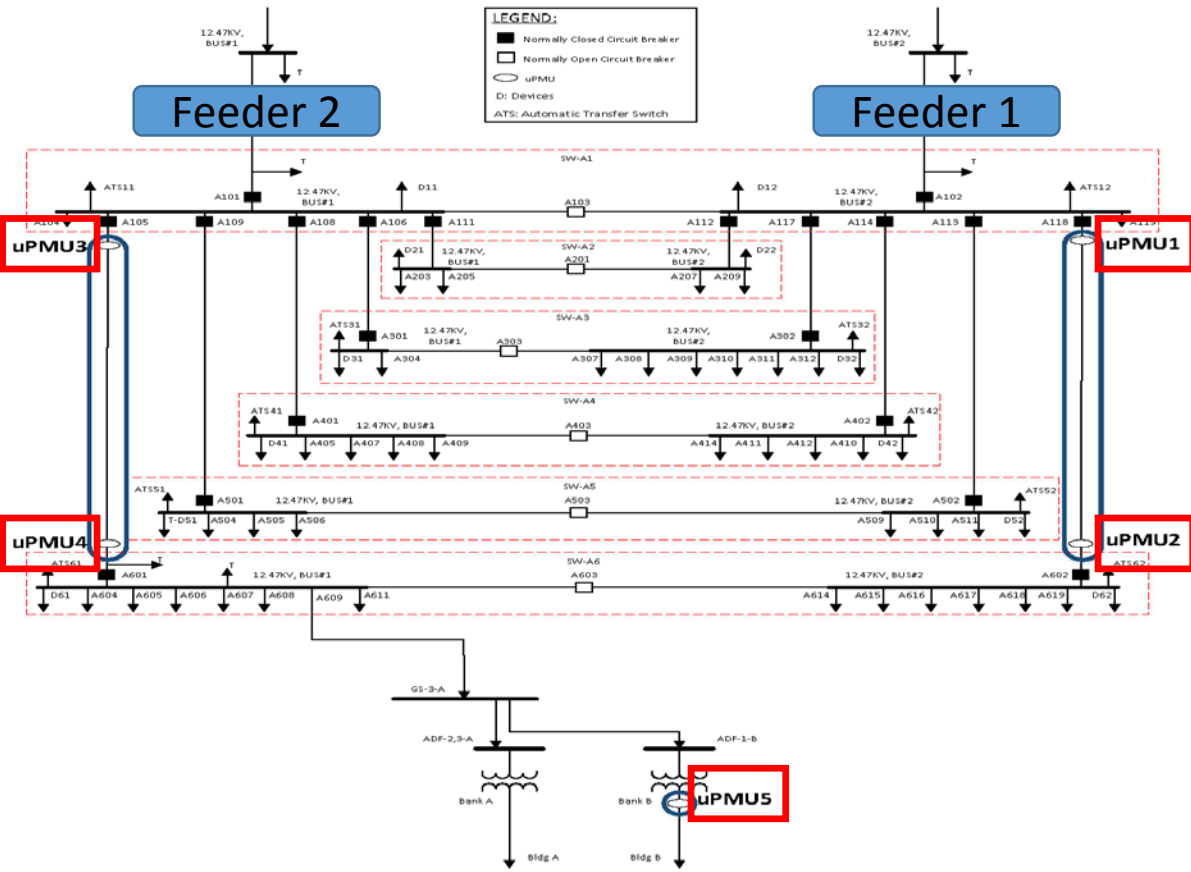
since $\frac{1}{T} \sum_{n=0}^{N-1} \mathbf{y}_{ij}[n] e^{-j2\pi f n T} = \mathbf{Y}_{ij}(f_0 + f) H(f)$ where $T = \frac{1}{120}$

Situational Awareness





- Significantly more information vs event-triggered DSCADA.

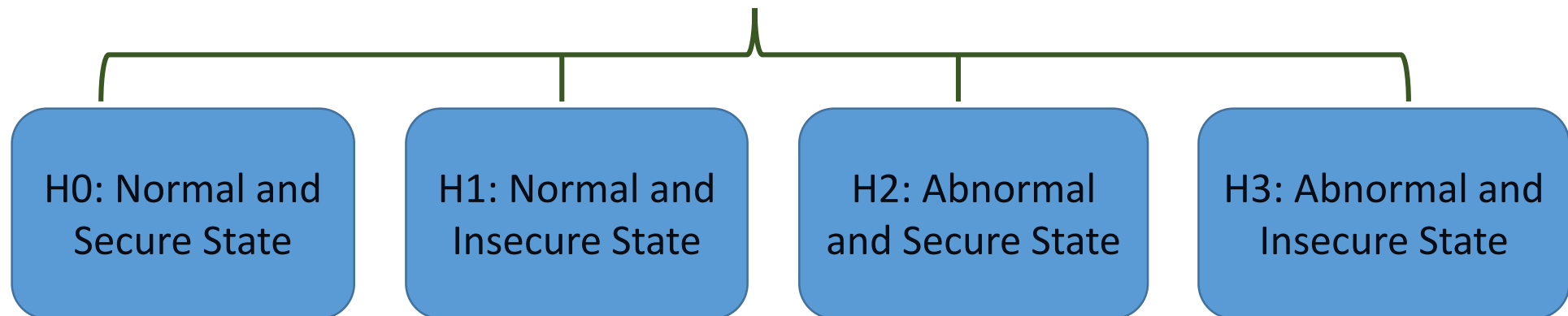




- Two voltage sags were captured on April. 16, 2015 between 10:20 AM – 10:21 AM PDT.
- The voltage sags can be seen in all the μ PMUs \rightarrow 2 separate distribution circuits impacted.
- It led to loss of some loads.

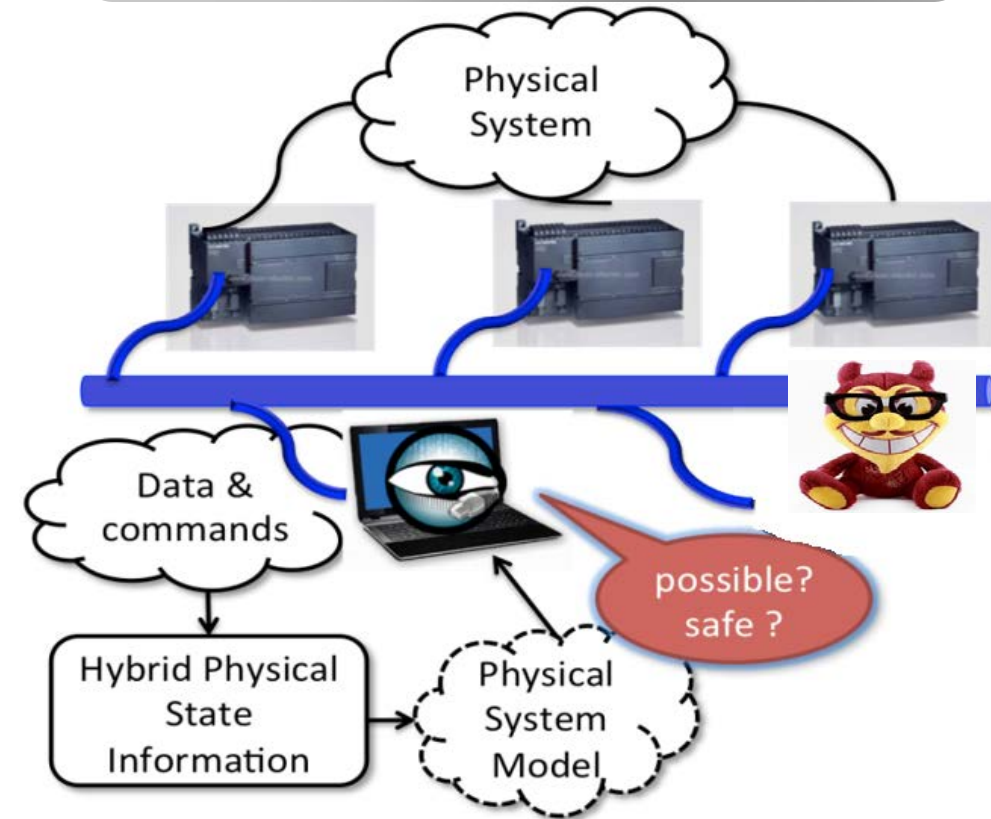
How to Utilize μ PMU Data for Security?

- Deployment of μ PMUs significantly increases the detection and classification capabilities of distribution operators.
- Many cyber-attacks targeting the physical layer leave footprints in the μ PMU data. 
- Detected μ PMU data anomalies + knowledge of grid operation
 grid security status hypotheses testing.



How to leverage Physics?

- Collect real-time measured data from micro phasor measurement units (μ PMUs) in the power distribution grid that reflect the physical condition of the system.
- Collect cyber network traffic to and from points in the distribution grid using Bro Intrusion Detection System.
- Using models of distribution grid state, analyze the distribution grid for unsafe operation.
- When anomalies are found, compare deviations from μ PMUs with SCADA traffic to determine if cyber event is at cause.



Data Analysis

μ PMU data functions of interest to be inspected for anomalies are:

✓ Voltage magnitude

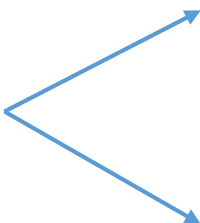
✓ Frequency

✓ Current magnitude

✓ Active power

✓ Reactive power

✓ Governing laws of Physics



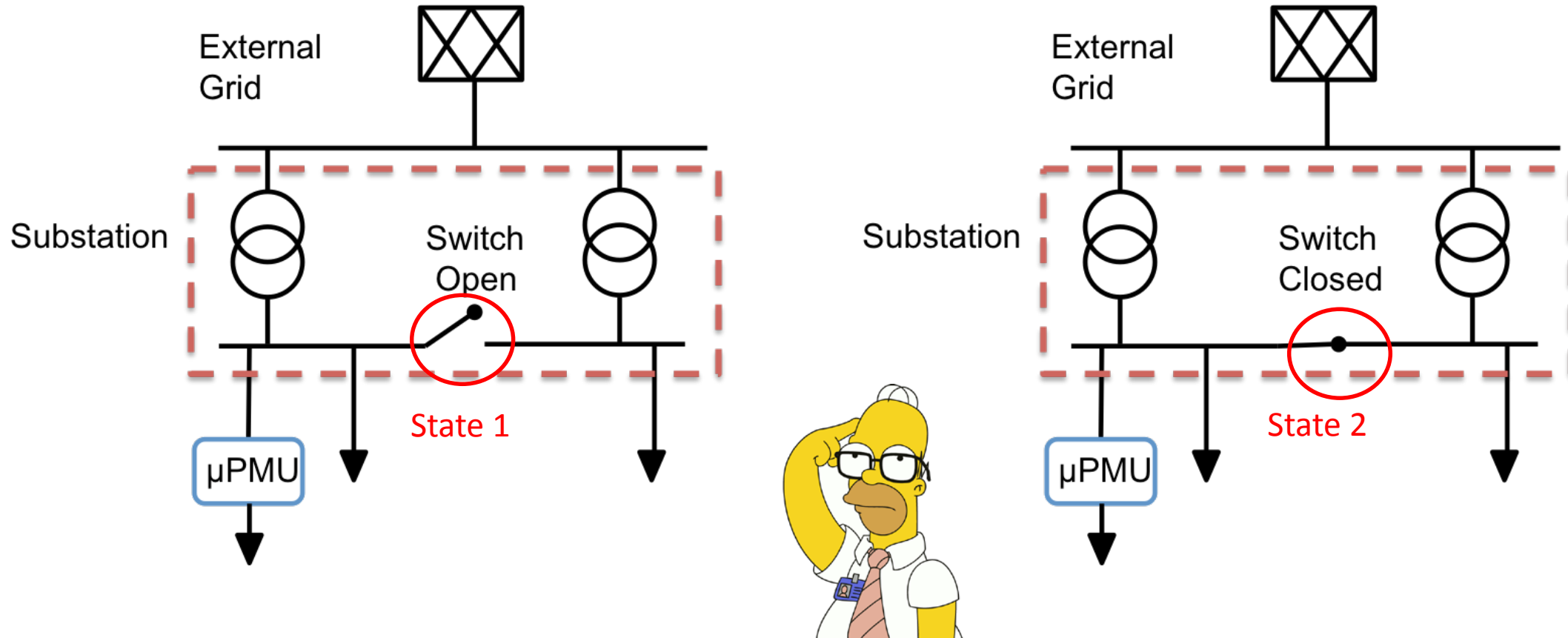
Validity of quasi steady-state regime using single or multiple μ PMU data.

Source impedance Thevenin changes.

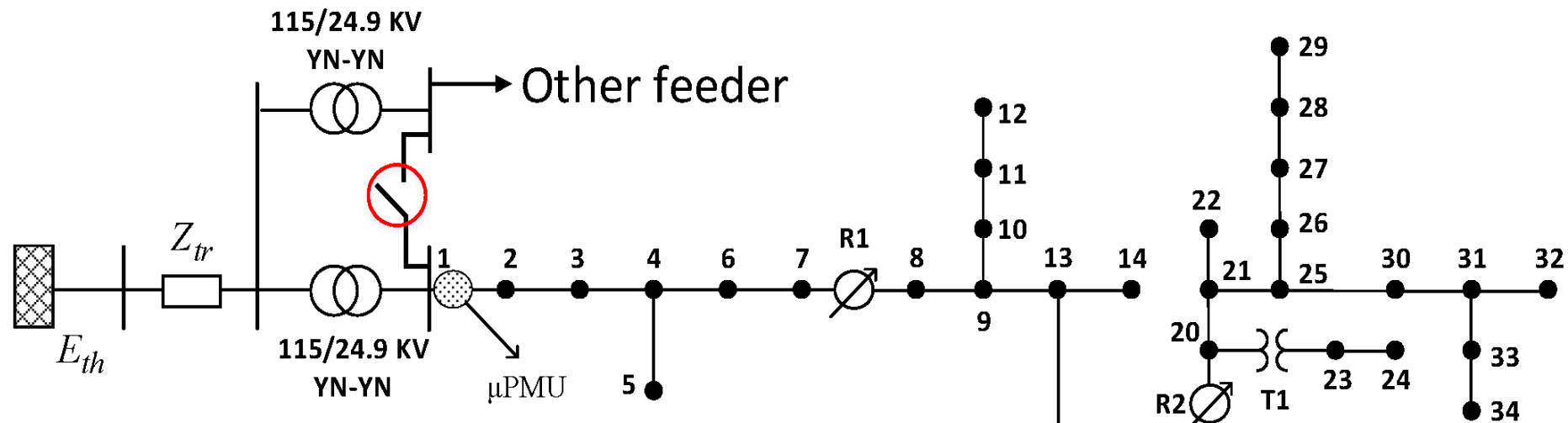
Example: Detecting Reconnaissance Attacks

- Attackers are likely to test their ability to control devices/switches prior to attack
- Ukraine attack of December 23rd 2015
 - Attackers appeared to have gained access more than 6 months prior to attack¹
 - Believed that they tested their capabilities prior to deployment.
- Can we detect these tests and inform operators?
 - Passively monitor and learn networks steady-state behavior
 - Once change has been detected notify operator
 - Operator confirms whether change was intentional or potential attack

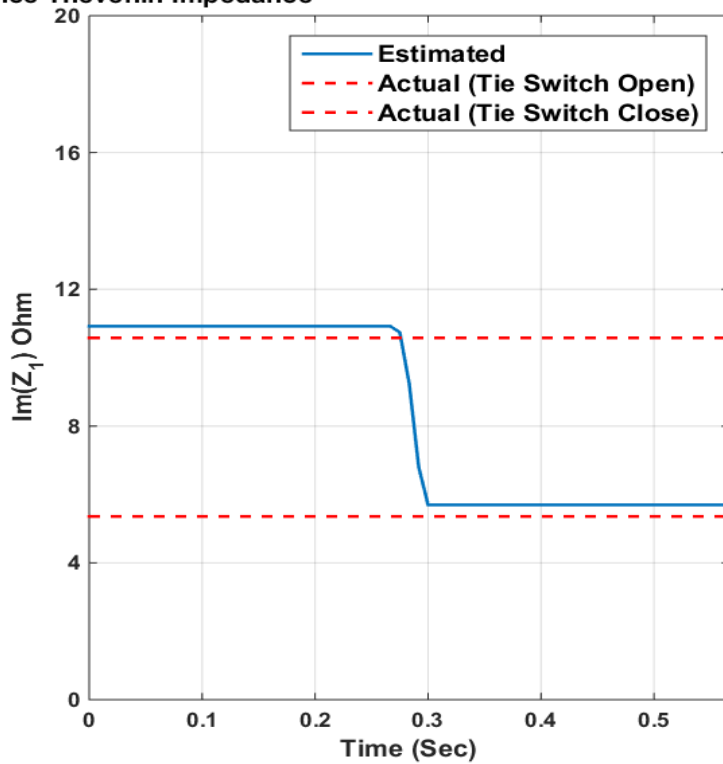
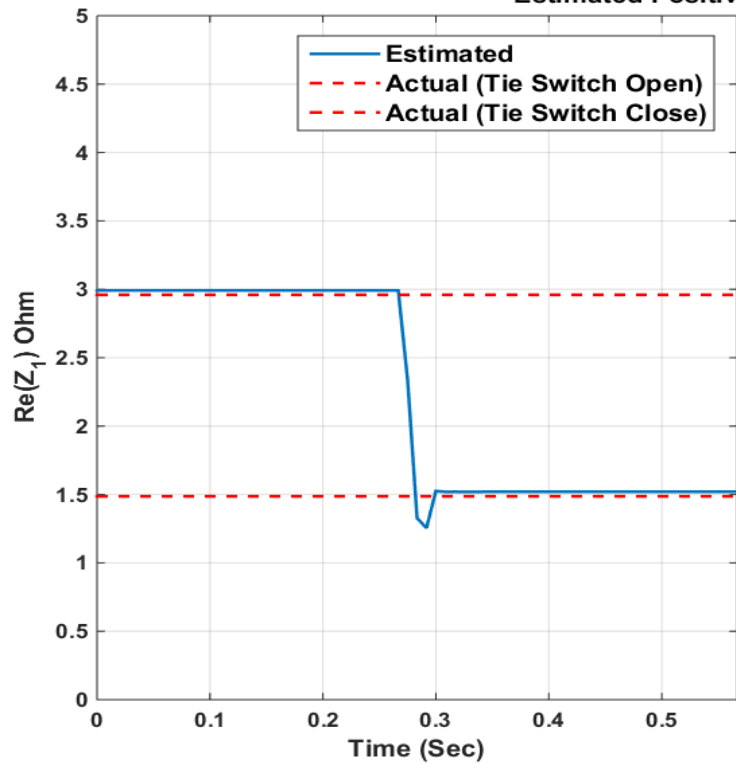
Use Case: Detecting Operation of Bus Tie Switch



- If we are sitting outside the substation can we detect a change of the bus-tie switch?
- Calculation of Thevenin Equivalent Impedance of grid as seen from μ PMU can detect such a change - Inform operators of change in status of bus-tie switch.



Estimated Positive Sequence Thevenin Impedance





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