SE 320
Control Systems

TR 10:00am - 11:20am
Location: TBD

Instructor: Prof. Yingying Li, (*yl101@illinois.edu*)
Office Hours: Thursdays, 11:30am-12:30am
Location: Coordinated Science Lab: Room 347

TA: Raunak Sengupta (*raunaks2@illinois.edu*)
Office Hours: TBD

Required Text: *Feedback Control Systems:* Fifth Edition,
by Charles L. Phillips and John M. Parr, Prentice-Hall publ.

Specific Course Information:

- **Course Description:** Fundamental control systems and control systems technology. Sensors, actuators, modeling of physical systems, design and implementation of feedback controllers; operational techniques used in describing, analyzing and designing linear continuous systems; Laplace transforms; response via transfer functions; stability; performance specifications; controller design via transfer functions; frequency response; simple nonlinearities.
- **Prerequisites:** CS101, MATH 285, & TAM212, Credit or Concurrent registration in ECE211.
- **Labs:** The information related to the labs can be found on: http://coecsl.ece.illinois.edu/se320/. Labs will not start until the week of February 19th.

Assignments:

- There will be **5 homeworks** posted approximately every other week. Homeworks and their solutions will be posted in Canvas.illinois.edu. The students should return their answers by the specified deadline by scanning or taking a photo of their solutions and uploading them on Canvas. Three problems will be selected "randomly" from each assignment for grading. Solutions for all problems will be provided.
- **No late homeworks** will be accepted. However, each student's lowest homework score will be dropped before course grades are computed. It is important to write your solution clearly as it may affect your grades. No collaboration or other solution sources are allowed on the problems assigned for homeworks or exams. Otherwise, UIUC student code § 1-402 on academic dishonestly will be followed.

Exams:

- There will be **one midterm exam** during the semester. Tentative Date: Thursday, March 14, 10am-12pm. Location: TBD.

- There will be **one final exam**. Time and location: TBD.
- For both the midterm and the final exams,
  - The exams are closed book, closed notes, closed homeworks. Only notes on both sides of a single A4 sheet is allowed.
  - You may use your calculator provided it has no wi-fi capabilities.
  - No cellphones allowed during the test.

TENTATIVE COURSE OUTLINE:

Reading	Topics	Lectures
Chapter 1:	Introduction to Control Systems	Week 1
Appendix B:	Laplace Transforms definition of Laplace transform and inverse Laplace transform; examples of common transforms; properties and theorems	Weeks 1-2
Chapter 2: **Sec. 1-3; 5-12**	Mathematical models for physical systems circuits, mechanical systems, electromechanical systems transformers and gears, more examples	Weeks 2-4
Chapter 4:	System Responses to Inputs responses in time-domain and frequency domain; design specifications	Weeks 4-5
Chapter 5:	Closed-loop Systems stability; transient response and steady state response; sensitivity	Weeks 5-7
Chapter 6:	Stability Analysis history and notions of stability; Routh-Hurwitz criterion; roots of the characteristic equation	Weeks 8-9
Chapter 8:	Frequency Response Analysis Frequency responses; Bode diagrams; Nyquist Criterion	Weeks 10-12
Chapter 9:	Frequency Response Design gain compensation; lag and lead compensation; lag-lead compensation PID design and implementation	Weeks 13-14

Course Grade Composition:

Item	% of grade
Homework Problem Sets	40%
Midterm Exam	20%
Final Exam	20%
Lab Report	20%

- Total Score ≥ 94: A+, Total Score ≥ 87: A, Total Score ≥ 83: A-
- Total Score ≥ 78: B+, Total Score ≥ 74: B, Total Score ≥ 70: B-
- Total Score ≥ 67: C+, Total Score ≥ 64: C, Total Score ≥ 60: C-
- Total Score ≥ 50: D, Total Score < 50: F.