SE 320 Control Systems TR 12:30 pm-1:50 pm, Fall 2023 2310 Everitt Laboratory (in-person lectures)

Instructor:	Rasoul Etesami (<i>etesami1@illinois.edu</i>) Office Hours: Thursday 4pm-5pm via Zoom Zoom Link: https://illinois.zoom.us/j/88363702321?pwd=cElhME1SMjlKNnB2M1B6SXkzZzdzQT09 Zoom Passcode: 529483
TAs:	Abbas Bataleblu (<i>abbasb2@illinois.edu</i>), Office Hours:TBD Carolina Carvalho (<i>leite2@illinois.edu</i>), Office Hours: TBD Sara Kohtz (<i>skohtz2@illinois.edu</i>), Office Hours: TBD Ruolei Wang (<i>ruoleiw2@illinois.edu</i>), Office Hours: TBD
Required Text:	<u>Feedback Control Systems:</u> Fifth Edition, 2010 by Charles L. Phillips and John M. Parr, Prentice-Hall publ.

Specific Course Information

- Course Description: Fundamental control systems and control systems technology. Sensors, actuators, modeling of physical systems, design and implementation of feedback controllers; operational techniques used in describing, analyzing and designing linear continuous systems; Laplace transforms; response via transfer functions; stability; performance specifications; controller design via transfer functions; frequency response; simple nonlinearities.
- Prerequisites: CS101, MATH 285, & TAM212, Credit or Concurrent registration in ECE211
- Labs: The information related to the labs can be found on: http://coecsl.ece.illinois.edu/se320/. The first lab starts on September 26.

Assignments and Exams:

- There will be **6 homeworks** posted approximately every other week. Homeworks and their solutions will be posted in *Canvas.illinois.edu*. The students should return their answers by the specified deadline by scanning or taking a photo of their solutions and uploading them on Canvas. Two or three problems will be selected "randomly" from each assignment for grading. Solutions for all problems will be provided.
- No late homeworks will be accepted. However, each student's lowest homework score will be dropped before course grades are computed. It is important to write your solution clearly as it may affect your grades. No collaboration or other solution sources are allowed on the problems assigned for homeworks or exams. Otherwise, UIUC student code § 1-402 on academic dishonestly will be followed.
- There will be one midterm exam during the semester which will be in the usual classroom 2310 Everitt Lab. Tentative Date: Oct 13, 12pm-2pm.
- There will be one final exam which will be on Tuesday Dec 12, 8am-11 am.

• For the students who need accommodation, please submit your forms no later than September 15. **Tentative Course Outline:**

Reading	Topics	Lectures
Chapter 1	Introduction to Control Systems	Week 1
Appendix B	Laplace Transforms: definition of Laplace transform and inverse Laplace transform; examples of common transforms; properties and theorems	Weeks 1-2
Chapter 2	Mathematical Models for Physical Systems: circuits, mechanical systems, electromechanical systems transformers and gears, more examples	Weeks 2-4
Chapter 4	System Responses to Inputs: responses in time-domain and frequency domain; design specifications	Weeks 4-5
Chapter 5	Closed-loop Systems: stability; transient response and steady state response; sensitivity	Weeks 5-7
Chapter 6	Stability Analysis: history and notions of stability; Routh-Hurwitz criterion; roots of the characteristic equation	Weeks 8-9
Chapter 8	Frequency Response Analysis: frequency responses; Bode diagrams; Nyquist Criterion	Weeks 10-12
Chapter 9	Frequency Response Design: gain compensation; lag and lead compensation; lag-lead compensation PID design and implementation	Weeks 13-14

Course Grade Composition:

	Item	% of grade
	Homework Problem	Sets 40%
	Midterm Exam	20%
	Final Exam	20%
	Lab Reports	20%
• Total Score ≥ 94 : A+,	Total Score ≥ 87 : A,	Total Score ≥ 83 : A-
• Total Score \geq 78: B+,	Total Score \geq 74: B,	Total Score \geq 70: B-
• Total Score \geq 67: C+,	Total Score ≥ 64 : C,	Total Score ≥ 60 : C-
• Total Score ≥ 50 : D,	Total Score < 50 : F.	